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Generalized $N = 1$ and $N = 2$ structures in M-theory and type II orientifolds

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ABSTRACT

We consider M-theory and type IIA reductions to four dimensions with $N = 2$ and $N = 1$ supersymmetry and discuss their interconnection. Our work is based on the framework of Exceptional Generalized Geometry (EGG), which extends the tangent bundle to include all symmetries in M-theory and type II string theory, covariantizing the local U-duality group $E_{7(7)}$. We describe general $N = 1$ and $N = 2$ reductions in terms of $SU(7)$ and $SU(6)$ structures on this bundle and thereby derive the effective four-dimensional $N = 1$ and $N = 2$ couplings, in particular we compute the Kähler and hyper-Kähler potentials as well as the triplet of Killing prepotentials (or the superpotential in the $N = 1$ case). These structures and couplings can be described in terms of forms on an eight-dimensional tangent space where $SL(8) \subset E_7$ acts, which might indicate a description in terms of an eight-dimensional internal space, similar to F-theory. We finally discuss an orbifold action in M-theory and its reduction to O6 orientifolds, and show how the projection on the $N = 2$ structures selects the $N = 1$ ones. We briefly comment on new orientifold projections, U-dual to the standard ones.

Contents

1	Introduction	2
2	Exceptional Generalized Geometry (EGG)	3
2.1	An eight-dimensional tangent space T_8	3
2.2	M-theory and $GL(7)$ decompositions	4
3	Supersymmetric reductions of M-theory in EGG	5
3.1	$N = 2$ reductions and $SU(6) \times SU(6)$ structures	6
3.2	$N = 2$ reductions and $SU(4)$ structure on T_8	7
3.3	$N = 1$ reductions	11
3.4	$N = 2$ in the language of $N = 1$	12
4	Type IIA reductions	13
4.1	Type IIA and $GL(6)$ decompositions	13
4.2	$N = 2$ and $N = 1$ reductions	15
5	From $N = 2$ to $N = 1$: Orientifolding and orbifolding in EGG	15
5.1	Orbifold action on T_8 and its reduction to M-theory	16
5.2	Further descent to type IIA	17
5.2.1	O6 orientifolds	17
5.2.2	Type IIB orientifolds	19
5.2.3	New Z_2 projections	19
5.2.4	Kähler subspaces	20
6	Discussion	22
A	$E_{7(7)}$ group theory	23
A.1	$E_{7(7)}$ group theory in terms of $SL(8)$ representations	23
A.2	The relation to $SU(8)$ representations	25
B	Technical computations	26
B.1	The $N = 1$ superpotential	26
B.2	The $N = 2$ prepotentials	28

1 Introduction

It has been a long-standing problem to understand more general flux backgrounds in string theory. The most successful tool for this task has been supersymmetry, since it reduces the second-order equations of motion to first-order supersymmetry equations that are much simpler to solve and provides non-renormalization theorems for certain sets of couplings. The simplest string backgrounds are Ricci-flat geometries that admit a number of covariantly constant spinors. However, in the presence of fluxes, the first-order supersymmetry equations become more involved, as all bosonic fields of string theory appear in these equations. The global bosonic symmetries of the massless string spectrum then can help to write these first-order equations in a simpler form. This is the approach of generalized geometry. The introduction of a generalized tangent bundle covariantizes these symmetries by combining the diffeomorphisms and gauge transformations of the gauge fields into a single vector bundle. The metric on this bundle then includes, besides the metric, the other massless bosonic fields. The idea was first applied to the T-duality group that transforms the metric and the B-field into each other. This description goes by the name of Generalized Complex Geometry [1].

More recently, the formalism was extended to the U-duality group of type II string theory to also include its Ramond-Ramond fields and to M-theory, covariantizing its three-form gauge field [2–5]. In both cases the covariantized symmetry group relevant to compactify to four dimensions is $E_{7(7)}$, and the generalized tangent bundle of type IIA is recovered from the one of M-theory by dimensional reduction. All possible supersymmetric backgrounds of type II and M-theory can then be understood as (generalized) G -structure backgrounds, where G is, depending on the number of supercharges, a subgroup of $SU(8)$ (the maximal compact subgroup of $E_{7(7)}$).¹ The first-order supersymmetry equations can then be written in a covariant way [6–8]. Furthermore, G -structure backgrounds that solve the equations of motion but not the first-order supersymmetry conditions can usually be understood as backgrounds with spontaneously broken supersymmetry. In this sense, generalized geometry serves as an off-shell supersymmetric formulation for general G -structure backgrounds.

Generalized G structures are characterized by fundamental objects (defined by bispinors) in certain representations of $E_{7(7)}$ such that their common stabilizer is exactly G . These fundamental objects determine the generalized metric (which is stabilized by $SU(8)$) and thereby the entire bosonic supergravity background. The first-order supersymmetry conditions are resembled by first-order differential equations on them. Moreover, the couplings of the off-shell supersymmetric formulations are given in terms of tensorial combinations of these fundamental objects into $E_{7(7)}$ singlets.

A major aim of this work is to understand $SU(7)$ and $SU(6)$ structures in M-theory and type II, as they correspond to backgrounds with the off-shell structure of four-dimensional $N = 1$ and $N = 2$ supergravity. $SU(7)$ structures in M-theory have already been discussed to some extent in [3], $SU(6)$ structures in type IIA have already been discussed in [4]. Of particular interest in our discussion will be the existence of an eight-dimensional intermediate bundle between the tangent and the generalized tangent bundle that admits the action of $SL(8) \subset E_{7(7)}$. This might indicate the existence of

¹Often these are called generalized G -structures as they are structures on the generalized tangent space, as opposed to usual G -structures on the tangent space.

a twelve-dimensional theory (similar to F-theory) in which some of the charges will be geometrized. $SU(7)$ and $SU(6)$ structures are related to $Spin(7)$ and $SU(4)$ structures in $SL(8)$.

After we briefly review the $E_{7(7)}$ -covariant formalism of exceptional generalized geometry in Section 2, we will discuss $SU(7)$ and $SU(6)$ structures in M-theory in Section 3. In particular, we will discuss all classical couplings in these backgrounds. Subsequently, we will relate these results to the equivalent structures in type IIA string theory in Section 4. While $SU(6)$ structures descend in a straight-forward way, $SU(7)$ -structures are related to O6-orientifold backgrounds in type IIA. Moreover, $SU(6)$ and $SU(7)$ structures should be related by involutions that project out half of the supersymmetry, such as orbifolding and orientifolding in M-theory and type II string theory. In Section 5 we will show how an $SU(7)$ structure is obtained from an $SU(6)$ structure via such involutions. In particular, we will determine the $N = 1$ couplings in terms of the $N = 2$ parent theory. Finally, we will identify the involutions given by standard orbifolding and orientifolding in M-theory and type II string theory and discuss a few new involutions, for instance an involution creating objects with tension and charge opposite to those of NS5-branes. We conclude with a summary of the results and some outlook. Appendix A contains all the relevant formulae concerning $E_{7(7)}$ representations, and Appendix B presents the details of some of the calculations done along the paper.

2 Exceptional Generalized Geometry (EGG)

In this section we review the basic concepts of Exceptional Generalized Geometry (EGG), emphasizing the role of the eight-dimensional intermediate tangent bundle T_8 . The idea of EGG is to covariantize the U-duality group $E_{7(7)}$ in M-theory and type II compactifications to four dimensions. Though only torus compactifications admit globally the action of the U-duality group, locally any background admits it, as the tangent space is isomorphic to $\mathbb{R}^7$ ($\mathbb{R}^6$). In EGG the internal seven- (or six-)dimensional tangent bundle of an M-theory (type II) compactification to four dimensions is enlarged to a 56-dimensional exceptional generalized tangent bundle such that the U-duality symmetry group $E_{7(7)}$ acts linearly on it. Thereby, the U-duality group promotes to a geometric action on this bundle. As the U-duality group maps all bosonic supergravity degrees of freedom into each other, EGG gathers them all in a metric on this exceptional generalized tangent bundle. The patching of the exceptional generalized tangent bundle [3] resembles the global aspects of the compactification. More details can be found in [2–5].

2.1 An eight-dimensional tangent space T_8

In the case of compactifications of type II, the exceptional tangent bundle combines the string internal momentum and winding charges (6+6 elements), their magnetic duals (another 6+6) as well as all the D-brane charges (32 elements). These together form the fundamental **56** representation of E_7 . In M-theory, it is a result of combining momentum and its dual (Kaluza-Klein monopole charge) (7+7) together with M2 and M5-brane charges (21+21). These charges can be combined into $SL(8, \mathbb{R})$ representations. We can think of this group as acting on an 8-dimensional tangent bundle T_8 , which will be split

into $7 + 1$ for M-theory, and further split into $6 + 1 + 1$ for type IIA. Of course there is a priori no eight-dimensional manifold with a tangent bundle T_8 appearing in M-theory or type IIA. Therefore, T_8 should be seen as some kind of generalized tangent bundle. In terms of $SL(8, \mathbb{R})$ representations, the fundamental of E_7 decomposes as

$$\begin{aligned} E &= \Lambda^2 T_8 \oplus \Lambda^2 T_8^* , \\ \mathbf{56} &= \mathbf{28} \oplus \mathbf{28}' . \end{aligned} \tag{2.1}$$

Similarly, for the adjoint we have

$$\begin{aligned} A &= (T_8 \otimes T_8^*)_0 \oplus \Lambda^4 T_8^* , \\ \mathbf{133} &= \mathbf{63} \oplus \mathbf{70} , \end{aligned} \tag{2.2}$$

where the subscript 0 denotes traceless. We will also need the **912** representation, which splits according to

$$\begin{aligned} N &= S^2 T_8 \oplus (\Lambda^3 T_8 \otimes T_8^*)_0 \oplus S^2 T_8^* \oplus (\Lambda^3 T_8^* \otimes T_8)_0 , \\ \mathbf{912} &= \mathbf{36} \oplus \mathbf{420} \oplus \mathbf{36}' \oplus \mathbf{420}' , \end{aligned} \tag{2.3}$$

where S^2 denotes symmetric two-tensors.

When we later consider spinors it is also useful to use the maximal compact subgroups of the groups that are involved. The maximal compact subgroup of E_7 is $SU(8)$, and the group-theoretical decompositions are completely analogous to the $SL(8, \mathbb{R})$ case and are given by (2.1-2.3). Note though that the $SU(8)$ that transforms the spinors is not the compact subgroup $SU(8)$ of $SL(8)$ that acts on T_8 . Nevertheless the two $SU(8)$ subgroups are related by some $E_{7(7)}$ transformation and the decomposition of $E_{7(7)}$ representations is the same in both cases. More details can be found in Appendix A.2. When we then consider $SL(8, \mathbb{R})$, spinors transform under the corresponding spin group $Spin(8)$ and its maximal compact subgroup $SO(8)$. Note that for $Spin(8)$, we can impose a Majorana-Weyl condition on the spinor. The Weyl-spinors are in one-to-one correspondence to $Spin(7)$ spinors that are considered in the M-theory compactification.

2.2 M-theory and $GL(7)$ decompositions

For compactifications of M-theory on seven-dimensional manifolds, we should decompose further the $SL(8)$ into $GL(7)$ representations, or in other words split the 8-dimensional dual vector bundle T_8^* into a 7-dimensional one T_7^* , plus a scalar piece. Choosing an overall power of the 7-dimensional volume form to get the correct embedding in $SL(8)$ (see more details in [3]), we get

$$\begin{aligned} T_8^* &= (\Lambda^7 T_7^*)^{-1/4} \otimes (T_7^* \oplus \Lambda^7 T_7^*) \\ \mathbf{8} &= \mathbf{7} \oplus \mathbf{1} \\ \rho_a &= (\rho_m, \rho_8) \end{aligned} \tag{2.4}$$

where ρ is some one-form, and $a = 1, \dots, 8$, $m = 1, \dots, 7$. Note that the eight-form $\rho_1 \wedge \dots \wedge \rho_8$ is just one on T_8 . This fits nicely with the fact that only $SL(8)$ acts on this

bundle. This implies that the fundamental **56** representation (2.1) decomposes as

$$\begin{aligned} E_M &= (\Lambda^7 T_7)^{1/2} \otimes (T_7 \oplus \Lambda^2 T_7^* \oplus \Lambda^5 T_7^* \oplus (T_7^* \otimes \Lambda^7 T_7^*)) , \\ \mathbf{56} &= \mathbf{7} \oplus \mathbf{21} \oplus \mathbf{21} \oplus \mathbf{7} \end{aligned} \quad (2.5)$$

corresponding respectively to momentum, M2- and M5-brane charge, and KK monopole charge.

In turn, the adjoint (2.2) decomposes into

$$\begin{aligned} A &= T_7 \otimes T_7^* \oplus \Lambda^6 T_7 \oplus \Lambda^6 T_7^* \oplus \Lambda^3 T_7 \oplus \Lambda^3 T_7^* , \\ \mathbf{133} &= \mathbf{48} \oplus \mathbf{1} \oplus \mathbf{7} \oplus \mathbf{7} \oplus \mathbf{35} \oplus \mathbf{35} \end{aligned} \quad (2.6)$$

We recognize here the $GL(7)$ adjoint (first term), and the shifts of the M-theory 3-form potential A_3 (last term) and its 6-form dual A_6 (fourth term). These build up the geometric subgroup of transformations that are used to patch the exceptional tangent bundle. The other pieces correspond to “hidden symmetries”, very much like the β -transformations in generalized geometry. Note that A_3 and A_6 come respectively from the **70** and **63** representations of $SL(8)$ in (2.2), i.e. they embed into the $SL(8)$ representations in (2.2) as

$$A_{\text{shifts}} = \left(\hat{A} \otimes \rho_8, A_4 \right) , \quad (2.7)$$

where we defined the four-form

$$A_4 \equiv A_3 \wedge \rho_8 , \quad (2.8)$$

and the vector

$$\hat{A} \equiv (\text{vol}_7)^{-1} \lrcorner A_6 , \quad (2.9)$$

with $\lrcorner$ meaning the full contraction of A_6 with $(\text{vol}_7)^{-1}$.

3 Supersymmetric reductions of M-theory in EGG

In this section we review reductions of M-theory preserving $N = 2$ and $N = 1$ supersymmetry in the language of Exceptional Generalized Geometry following [3,4]. In the $N = 2$ case, we show how an $SU(4)$ structure on T_8 emerges, and write the EGG structures in terms of the complex and symplectic structures on this space.

To get a supersymmetric effective four-dimensional theory, there should exist nowhere-vanishing spinors η_i on the seven-dimensional internal space such that the eleven dimensional spinor can be decomposed as (for spinor conventions, see [3])

$$\epsilon = \xi_+^i \otimes \eta_i^c + \xi_-^i \otimes \eta_i , \quad (3.1)$$

where $\xi_\pm^i$ are four-dimensional Weyl spinors, η_i are complex $Spin(7)$ spinor and $i = 1, \dots, N$ determines the amount of 4D supersymmetry. When we embed $Spin(7)$ into $Spin(8)$, we can choose η_i to be of positive chirality with respect to $Spin(8)$, which means that we can take η_i to transform in the **8** of $SU(8)$. Note that there exists a Majorana condition for $Spin(7)$ (and also for $Spin(8)$) so that actually the real and imaginary parts of η_i are independent spinors. Both the real and imaginary part of η_i are stabilized by a

$Spin(7)$ subgroup in $SL(8, \mathbb{R})$, respectively. Therefore, inside $SL(8, \mathbb{R})$ each complex spinor η_i defines a pair of $Spin(7)$ structures. Inside $E_{7(7)}$ though, each η transforms in the fundamental of $SU(8)$ and its real and imaginary parts are not independent any more, as they transform into each other under $SU(8)$. Consequently, a single η defines an $SU(7)$ structure [3], and in general N non-mutually parallel spinors define an $SU(8-N) \subset E_{7(7)}$ structure.

3.1 $N = 2$ reductions and $SU(6) \times SU(6)$ structures

For reductions with $N = 2$ supersymmetry in four-dimensions, there should be a pair of globally defined no-where vanishing (and nowhere parallel) $SU(8)$ spinors η_1, η_2 . As explained above, each of these spinors can be complex so that $\text{Re } \eta_i$ and $\text{Im } \eta_i$ each define an $SU(6)$ structure. Without loss of generality, we can take them to be orthogonal and having the same norm, namely

$$\bar{\eta}_i \eta_j = e^{-K_L/2} \delta_{ij} , \quad (3.2)$$

where $i, j = 1, 2$ is an $SU(2)_R$ index, and we introduced an arbitrary normalization factor $e^{-K_L/2}$ which we will further discuss below. On the other hand, we have in general the following inner products

$$\eta_i^T \eta_j = c_{ij} , \quad (3.3)$$

for some complex 2×2 matrix $C = (c_{ij})$.²

The scalar degrees of freedom of $N = 2$ theories, coming from vector and hypermultiplets, are encoded respectively in an $SU(2)_R$ singlet and an $SU(2)_R$ triplet of bispinors [4]. The former embeds in the **28** representation of $SU(8)$, which appears in the fundamental **56** representation of E_7 , and in terms of the decomposition (2.1) reads

$$\hat{L}^{(0)} = \frac{1}{2}(\epsilon^{ij} \eta_i \otimes \eta_j, \epsilon^{ij} \bar{\eta}_i \otimes \bar{\eta}_j) , \quad \tilde{L}^{(0)} = \frac{1}{2}(-i \epsilon^{ij} \eta_i \otimes \eta_j, i \epsilon^{ij} \bar{\eta}_i \otimes \bar{\eta}_j) , \quad (3.4)$$

where for later convenience we have defined two real bispinors in the **28** and **$\bar{28}$** that are related to L by $L = \hat{L}^{(0)} + i \tilde{L}^{(0)}$. From $\hat{L}^{(0)}$ we can define also the almost complex structure J_L that relates real and imaginary parts of L , given by

$$J_L = 2 \hat{L} \times \hat{L} = L \times \bar{L} = (e^{-K_L/2} \delta_{ij} \eta_i \otimes \bar{\eta}_j - \frac{1}{4} e^{-K_L} 1, 0) . \quad (3.5)$$

where 1 is the identity matrix with $Spin(8)$ spinorial indices, δ_β^α .

Furthermore, the $SU(2)_R$ triplet transforms in the **63** adjoint representation of $SU(8)$, which is embedded in the **133** adjoint representation of E_7 , and reads in terms of the decomposition (2.2)

$$K_a^{(0)} = (\kappa e^{K_L/2} \sigma_a^i \delta^{kj} \eta_i \otimes \bar{\eta}_j, 0) \quad (3.6)$$

where σ_a are the Pauli sigma matrices and we introduced another normalization factor κ . Note that the product of L and K in the **56** vanishes, i.e.

$$K_a^{(0)} \cdot L^{(0)} = 0 , \quad (3.7)$$

²The matrix C is complex symmetric and in general not diagonalizable.

which means that the stabilizers of $L^{(0)}$ ($E_{6(2)} \subset E_{7(7)}$) and $K_a^{(0)}$ ($SO^*(12) \subset E_{7(7)}$) intersect in $SU(6)$. General L and K_a are then constructed by acting with the shift matrix A_{shifts} in the adjoint of $E_{7(7)}$ on them, i.e.

$$L = e^{A_{\text{shifts}}} L^{(0)} , \quad J_L = e^{A_{\text{shifts}}} J_L^{(0)} , \quad K_a = e^{A_{\text{shifts}}} K_a^{(0)} . \quad (3.8)$$

The Kähler potential for the space of structures L and the hyper-Kähler potential hyper-Kähler cone over the space of K_a has been given in [4]. The Kähler potential for L is given by the moment map for the rotation of L by a phase (generated by J_L) and can be expressed by the logarithm of the quartic invariant of $\hat{L}$ [4]

$$K_L = -\log \sqrt{-\frac{1}{4}(J_L, J_L)} = -\log \sqrt{-q(\hat{L})} = -\log \left(-\frac{i}{8} \langle L^{(0)}, \bar{L}^{(0)} \rangle \right) . \quad (3.9)$$

where $(\cdot, \cdot)$ refers to the trace in the adjoint, given in (A.7). The hyper-Kähler potential of the hyper-Kähler cone over the moduli space of K_a is determined by [4]

$$\kappa = \sqrt{-\frac{1}{4}(K_a, K_a)} . \quad (3.10)$$

It determines the normalization of the K_a by

$$K_a \cdot (K_b \cdot \nu) = -\frac{1}{2} \kappa^2 \delta_{ab} \nu + \kappa \epsilon_{abc} K_c \cdot \nu , \quad (3.11)$$

where ν is an arbitrary element in the 56 representation.

The supersymmetric couplings between the two objects L and K_a are given by the Killing prepotentials [4, 8]

$$P^a = \epsilon^{abc} (D_L K_b, K_c) , \quad (3.12)$$

and $D_L = \langle L, D \rangle - L \times D$ is the Dorfman derivative [5] along L , with D being the standard differential operator.³ Inserting this, we get [8]

$$P^a = \epsilon^{abc} (\langle L, D \rangle K_b, K_c) + 4\kappa (L, DK_a) . \quad (3.13)$$

3.2 $N = 2$ reductions and $SU(4)$ structure on T_8

In the last section we defined a general $SU(6)$ structure with an arbitrary product (3.3). Note that in general, the spinors η_i are complex, and real and imaginary part of each spinor, if they are never parallel, already define an $SU(6)$ structure, so in general we would have “ $SU(6) \times SU(6)$ ” structures (and secretly, a theory with more supersymmetries). In such a generic case, it is difficult to be more explicit as typically all $SL(8)$ components are present in L and K_a . The case of real (i.e. Majorana) spinors η_i simplifies the form of L and K_a and gives rise to a natural interpretation in terms of the bundle T_8 . The relation (3.3) reduces for real spinors to the normalization condition (3.2) so that

$$c_{ij} = e^{-K_L/2} \delta_{ij} . \quad (3.14)$$

³ $\langle L, D \rangle$ is the symplectic invariant (A.6), and $(L \times D)$ is the projection onto the adjoint in the product of two **56** elements, given in (A.8).

We will express now both $L^{(0)}$ and $K_a^{(0)}$ in (3.4) and (3.6) in terms of objects in $SL(8, \mathbb{R})$ representations. For this we define a pure spinor

$$\chi = \eta_1 + i\eta_2 \quad (3.15)$$

out of the real spinors η_i .⁴ We then find for $L^{(0)}$ and $K_a^{(0)}$ that

$$\begin{aligned} K_3^{(0)} \pm i K_1^{(0)} &= (\chi \otimes \chi^T, 0) , \\ J_L^{(0)} \pm i K_2^{(0)} &= (\chi \otimes \bar{\chi} - \frac{1}{4} e^{K_L/2} \mathbf{1}, 0) . \end{aligned} \quad (3.16)$$

On the other hand, the bispinors $\Phi_1 = \chi \otimes \bar{\chi}$ and $\Phi_2 = \chi \otimes \chi^T$ are a pair of compatible $O(8, 8)$ pure spinors that define an $SU(4)$ structure on T_8 , given by [1]

$$\Phi_1 = \frac{1}{4} e^{-K_L/2} \exp(-i e^{K_L/2} J_8^{(0)}) , \quad \Phi_2 = \Omega_4^{(0)} , \quad (3.17)$$

where we made the following definitions

$$\begin{aligned} J_8^{(0)} &= -i \bar{\chi} \gamma_{ab} \chi dx^a \wedge dx^b = \epsilon^{ij} \bar{\eta}_i \gamma_{ab} \eta_j dx^a \wedge dx^b , \\ \Omega_4^{(0)} &= -\frac{1}{4} \kappa e^{K_L/2} \chi^T \gamma_{abcd} \chi dx^a \wedge dx^b \wedge dx^c \wedge dx^d \\ &= -\frac{1}{4} \kappa e^{K_L/2} (\bar{\eta}_1 + i \bar{\eta}_2) \gamma_{abcd} (\eta_1 + i \eta_2) dx^a \wedge dx^b \wedge dx^c \wedge dx^d . \end{aligned} \quad (3.18)$$

In terms of the x^m we find

$$J_8^{(0)} = J + v^{(0)} \wedge \rho_8 , \quad J = \epsilon^{ij} \bar{\eta}_i \gamma_{mn} \eta_j dx^m \wedge dx^n , \quad (3.19)$$

$$\Omega_4^{(0)} = (\rho_8 + i v^{(0)}) \wedge \Omega , \quad \Omega = \iota_{\hat{\rho}_8} \Omega_4^{(0)} , \quad (3.20)$$

where the one-form $v^{(0)}$ is defined by⁵

$$v^{(0)} = \iota_{\hat{\rho}_8} \epsilon^{ij} \bar{\eta}_i \gamma_{ab} \eta_j dx^a \wedge dx^b . \quad (3.21)$$

The four-form $\Omega_4^{(0)}$ defines a complex structure $I_8^{(0)}$ by

$$\begin{aligned} (I_8^{(0)})^m{}_n &= \frac{1}{\kappa^2} (*_8 \text{Im } \Omega_4^{(0)})^{mpqr} (\text{Re } \Omega_4^{(0)})_{npqr} \\ &= \frac{1}{2\kappa^2} ((\hat{v}^{(0)})^m (\rho_8)_n - \hat{\rho}_8^m v_n^{(0)} + (\text{Im } \Omega)^{mpq} (\text{Re } \Omega)_{npq} - (\text{Re } \Omega)^{mpq} (\text{Im } \Omega)_{npq}) . \end{aligned} \quad (3.22)$$

In terms of these objects, the structure $L^{(0)}$ has the following $SL(8, \mathbb{R})$ decomposition (cf. (2.1))⁶

$$\begin{aligned} L^{(0)} &= \hat{L}^{(0)} + i \tilde{L}^{(0)} = (-\hat{\rho}_8 \wedge \hat{v}^{(0)} + e^{K_L} \text{vol}_8^{-1} \lrcorner (\frac{1}{2} \rho_8 \wedge v^{(0)} \wedge J \wedge J), i(\rho_8 \wedge v^{(0)} - J)) \\ &= (e^{K_L} \text{vol}_8^{-1} \lrcorner (\frac{1}{3!} J_8^{(0)} \wedge J_8^{(0)} \wedge J_8^{(0)}), -i J_8^{(0)}) \\ &= e^{i \rho_8 \wedge v^{(0)} \wedge J} \cdot (-\hat{\rho}_8 \wedge \hat{v}^{(0)}, 0) , \end{aligned} \quad (3.23)$$

⁴A complex $Spin(8)$ spinor χ is called pure if $\chi^T \chi = 0$.

⁵The hat denotes the vector dual to a one-form. In the special case that v is the one-form dy of a circle, one can reduce the theory to type IIA, where $v_m \gamma^{m8}$ then plays the role of chirality.

⁶For the generic case of complex spinors η_i , the form of $L^{(0)}$ is also given by Eq. (3.23), but in this case $J_8^{(0)}$ is complex, given by

$$J_8^{(0)} = \epsilon^{ij} \eta_i^T \gamma_{ab} \eta_j dx^a \wedge dx^b ,$$

and similarly for J and $v^{(0)}$.

where we have used (A.20) and $\text{vol}_8^{-1} \lrcorner$ means contraction with the eight-dimensional volume form, i.e. with the numeric epsilon tensor (the 8-dimensional space has no volume modulus). We see that $L^{(0)}$ can be understood as the shift of the bi-vector $-\hat{\rho}_8 \wedge \hat{v}$ by some imaginary four-form $i\rho_8 \wedge v^{(0)} \wedge J$.⁷ The almost complex structure relating real and imaginary part of $L^{(0)}$ given in (3.5) can be computed to be

$$J_{L^{(0)}} = (0, J_8 \wedge J_8) . \quad (3.24)$$

Similarly, using (3.16) and (A.21), we can determine $K_a^{(0)}$ for the decomposition (2.2) to be

$$\begin{aligned} K_1^{(0)} &= (0, \text{Im } \Omega_4^{(0)}) , \\ K_2^{(0)} &= (\kappa I_8^{(0)}, 0) , \\ K_3^{(0)} &= (0, \text{Re } \Omega_4^{(0)}) . \end{aligned} \quad (3.25)$$

From the Fierz identities (or from the $SU(2)$ algebra) it follows that $\Omega_4^{(0)}$ transforms holomorphically under $I_8^{(0)}$, and obeys

$$\Omega_4^{(0)} \wedge \Omega_4^{(0)} = 0 , \quad \Omega_4^{(0)} \wedge \bar{\Omega}_4^{(0)} = 2\kappa^2 \text{vol}_8 . \quad (3.26)$$

We also have $\iota_{\hat{v}^{(0)}} J = \iota_{\hat{\rho}_8} J = 0$, and $\frac{1}{3!} v \wedge J \wedge J \wedge J = e^{-2K_L} \text{vol}_7$ or in other words

$$\frac{1}{4!} J_8^{(0)} \wedge J_8^{(0)} \wedge J_8^{(0)} \wedge J_8^{(0)} = \frac{1}{3!} J \wedge J \wedge J \wedge v \wedge \rho_8 = e^{-2K_L} \text{vol}_8 . \quad (3.27)$$

Furthermore, the compatibility condition (3.7) of $L^{(0)}$ and $K_a^{(0)}$ implies $\iota_{\hat{v}^{(0)}} \Omega = 0$ and $J \wedge \Omega = 0$, or in other words

$$J_8^{(0)} \wedge \Omega_4^{(0)} = 0 . \quad (3.28)$$

Therefore $J_8^{(0)}$ and $\Omega_4^{(0)}$ define an $SU(4)$ structure on the eight-dimensional space T_8 , i.e. inside $SL(8, \mathbb{R})$.⁸ From the compatibility condition (3.7) it also follows that $g_8^{(0)}$ defined by

$$g_8^{(0)} = e^{K_L/2} J_8^{(0)} \cdot I_8^{(0)} , \quad (3.29)$$

is a symmetric object. Furthermore, explicit computation shows that $g_8^{(0)}$ is of the form

$$g_8^{(0)} = (\det g_7)^{-1/4} \begin{pmatrix} g_7 & 0 \\ 0 & \det g_7 \end{pmatrix} . \quad (3.30)$$

Similar to (3.29) we also find for the inverse metric $g_8^{(0)-1}$ the expression

$$g_8^{(0)-1} = e^{3K_L/2} I_8^{(0)} \cdot (\text{vol}_8^{-1} \lrcorner (\frac{1}{3!} J_8^{(0)} \wedge J_8^{(0)} \wedge J_8^{(0)})) . \quad (3.31)$$

General elements L , K_a in the orbit can be achieved from $L^{(0)}$, $K_a^{(0)}$ by the action of $E_{7(7)}$, cf. (3.8). The degrees of freedom that can modify the above embeddings are the remaining massless fields of M-theory, namely the three-form gauge field A_3 and its

⁷Note that this shift is not an $E_{7(7)}$ transformation because the four-form is not real.

⁸As stated above, these objects define an $SU(6)$ structure inside $E_{7(7)}$.

magnetic dual six-form field A_6 . Their action in $SL(8)$ language is shown in (2.7). This gives

$$\begin{aligned} L &= e^{A_4} (\text{vol}_8^{-1} \lrcorner (\frac{1}{3!} J_8 \wedge J_8 \wedge J_8), -i J_8) , \\ J_L &= -e^{A_4} (0, J_8 \wedge J_8) , \end{aligned} \quad (3.32)$$

and

$$\begin{aligned} K_1 &= e^{A_4} (0, \text{Im } \Omega_4) , \\ K_2 &= e^{A_4} (\kappa I_8, 0) , \\ K_3 &= e^{A_4} (0, \text{Re } \Omega_4) , \end{aligned} \quad (3.33)$$

where A_4 is defined in (2.8) and the shifted J and Ω_4 are

$$J_8 = J + v \wedge \rho_8 , \quad \Omega_4 = ((1 + i a_6^v) \rho_8 + i v^{(0)}) \wedge \Omega - i \rho_8 \wedge v^{(0)} \wedge \iota_{\hat{A}} \Omega \quad (3.34)$$

with $\hat{A}$ defined in (2.9), and

$$v = v^{(0)} - \iota_{\hat{A}} J , \quad a_6^v = \text{vol}_7^{-1} \cdot (v^{(0)} \wedge A_6) . \quad (3.35)$$

The symplectic and complex structure J_8 and Ω_4 are also compatible, which means $J_8 \wedge \Omega_4 = 0$. Finally, the almost complex structure $I_8^{(0)}$ is shifted so that $\Omega_4^{(0)}$ is replaced by Ω_4 in (3.22).

We see that the description of an $SU(6) \subset E_7$ structure in M-theory is completely analogous to the type II case discussed in [4], namely given by one object in the fundamental representation and a triplet in the adjoint. These are in turn described respectively by J_8 and Ω_4 , which define an $SU(4) \subset SL(8)$ structure, in a form that very much resembles the pure spinors $e^{-i J_8}$, Ω_4 of two generalized almost complex structures. We will come back to this in Section 4.

We turn now to the Kähler potentials and prepotentials for the space of structures L and (the hyper-Kähler cone over) K_a . They both have the expected form in terms of the $SU(4)$ structure objects J_8 and Ω_4 . The Kähler potential for L can be easily computed from (3.9) to be

$$K_L = -\frac{1}{2} \log(\frac{1}{4!} J_8 \wedge J_8 \wedge J_8 \wedge J_8) . \quad (3.36)$$

The hyper-Kähler potential of the hyper-Kähler cone over the moduli space of K_a is given by (3.10) and reads in terms of Ω_4 as

$$\kappa = \sqrt{\frac{1}{2} \Omega_4 \wedge \bar{\Omega}_4} . \quad (3.37)$$

Finally, the Killing prepotentials (3.13) are computed in Appendix B.2, using the differential operator D in the **56** representation that is given by the embedding

$$D = (0, \rho_8 \wedge d) . \quad (3.38)$$

The result of the computation is given by

$$\begin{aligned} P^3 + i P^1 &= -4\kappa \left(i J \wedge \rho_8 \wedge d\Omega_4^{(0)} + \iota_v \Omega_4^{(0)} \wedge \rho_8 \wedge dA_3 \right) , \\ P^2 &= e^{-K_L} \text{Im} \left((\mathcal{L}_{\hat{v}} \bar{\Omega}_4^{(0)}) \wedge \Omega_4^{(0)} \right) - 2\kappa^2 e^{K_L} \rho_8 \wedge J \wedge J \wedge v^{(0)} \wedge dv^{(0)} \\ &\quad + 4\kappa \rho_8 \wedge (dA_6 - (A_3 + i \kappa v^{(0)} \wedge J) \wedge dA_3) , \end{aligned} \quad (3.39)$$

where $\mathcal{L}_{\hat{v}}$ is the Lie derivative along v .

3.3 $N = 1$ reductions

For reductions with $N = 1$ supersymmetry, there is a single $Spin(8)$ internal spinor η , which defines an $SU(7)$ structure in $E_{7(7)}$.⁹ This structure can be encoded in a nowhere-vanishing object ϕ in the **912** representation of $E_{7(7)}$ [3]. The **912** decomposes in $SU(8)$ representations in the same way as for $SL(8)$, given in (2.3). In terms of this decomposition, we have

$$\phi^{(0)} = (2\eta \otimes \eta, 0, 0, 0) , \quad \bar{\phi}^{(0)} = (0, 0, 2\bar{\eta} \otimes \bar{\eta}, 0) , \quad (3.40)$$

with the normalization

$$\bar{\eta}\eta = e^{-K_\phi/2} . \quad (3.41)$$

Using (A.22) we can write this in terms of $SL(8)$ representations (2.3)

$$\phi^{(0)} = -(c(g_8^{(0)})^{-1}, g_8^{(0)} \cdot (\text{vol}_8^{-1} \lrcorner \phi_4^{(0)}), i c g_8^{(0)}, i(g_8^{(0)})^{-1} \cdot \phi_4^{(0)}) \quad (3.42)$$

where $g_8^{(0)}$ is the metric on T_8 (3.30), the complex constant c is defined by

$$\eta^T \eta = c , \quad (3.43)$$

and

$$\phi_{abcd}^{(0)} = \frac{3}{8} \eta^T \gamma_{abcd} \eta . \quad (3.44)$$

Note that at points where $|c| \neq e^{K_\phi/2}$ real and imaginary part of η actually define a (local) $SU(6)$ -structure. In terms of the split into $7 + 1$ in (2.4), this can be written as

$$\phi_4^{(0)} = \rho_8 \wedge \alpha_3 + * \alpha_3 , \quad (3.45)$$

where α_3 is a complex three-form that defines a $G_2 \times G_2$ -structure which reduces to a real three-form in the G_2 -structure case (i.e. when η is Majorana). Note that $\phi_4^{(0)}$ is self-dual as η is of positive chirality in $Spin(8)$.

A general element ϕ is obtained by

$$\phi = e^{A_{\text{shifts}}} \phi^{(0)} = -e^{A_4} (c g_8^{-1}, g_8 \cdot (\text{vol}_8^{-1} \lrcorner \phi_4), i c g_8, i g_8^{-1} \cdot \phi_4) , \quad (3.46)$$

where A_4 , defined in (2.8), acts by the E_7 adjoint action (A.11), while A_6 shifts the metric (3.30) by

$$g_8 = (\det g_7)^{-1/4} \begin{pmatrix} g_7 + (*_7 A_6)^2 & (\det g_7)^{1/2} *_7 A_6 \\ (\det g_7)^{1/2} *_7 A_6 & \det g_7 \end{pmatrix} , \quad (3.47)$$

and the 4-form

$$\phi_4 = \phi_4^{(0)} + \rho_8 \wedge \iota_{\hat{A}} *_7 \alpha_3 . \quad (3.48)$$

Note that the volume form vol_8 of the metric g_8 in (3.47) is still given by the eight-dimensional epsilon tensor (with entries ± 1 and 0), as there is no R_+ factor in $E_{7(7)}$ corresponding to the eight-dimensional volume. We will therefore sometimes abuse notation and make no distinction between an eight-form and a scalar.

The stabilizer of ϕ turns out to be indeed $SU(7)$ [3]. Therefore, the existence of ϕ is completely equivalent to η . We will denote the real and imaginary parts of ϕ by $\hat{\phi}$ and

⁹This spinor can have a real and imaginary part and thereby actually defines an $SU(7) \times SU(7)$ structure.

$\tilde{\phi}$. The product $\mathbf{912} \times \mathbf{912} \rightarrow \mathbf{133}$ gives us the generator $\mathcal{J}_\phi$ for the almost complex structure $e^{\mathcal{J}_\phi}$ related to ϕ . More precisely, we have

$$\mathcal{J}_\phi = 2\hat{\phi} \times \hat{\phi} , \quad (3.49)$$

which in terms of the $SL(8)$ decomposition (2.2) is

$$\mathcal{J}_\phi = e^{A_4} \cdot (I_\phi, \phi_4^r) , \quad (3.50)$$

with

$$(I_\phi)^a_b = -\frac{4}{3}(\text{vol}_8^{-1} \lrcorner \text{Re } \phi_4)^{acde} (\text{Im } \phi_4)_{bcde} \quad (3.51)$$

and

$$\phi_4^r = 14 \text{Re}(\bar{c}\phi_4) = \frac{1}{2}e^{K_\phi/2} \bar{\eta} \gamma_{abcd} \eta dx^a \wedge dx^b \wedge dx^c \wedge dx^d . \quad (3.52)$$

The Kähler potential K_ϕ in the orbit of ϕ is given by the quartic invariant in the $\mathbf{912}$ and turns out to be

$$\begin{aligned} K_\phi &= -\log \sqrt{-q(\hat{\phi})} = -\log \sqrt{-\frac{1}{4}(\mathcal{J}_\phi, \mathcal{J}_\phi)} = -\log \sqrt{-\frac{1}{4}\text{tr}(I_\phi^2)} - \frac{1}{2} \log \frac{1}{4!} \phi_4^r \wedge \phi_4^r \\ &= -\log \sqrt{-\frac{1}{4}\text{tr}((I_\phi^{(0)})^2)} - \frac{1}{2} \log \frac{1}{4!} \phi_4^{r(0)} \wedge \phi_4^{r(0)} , \end{aligned} \quad (3.53)$$

where in the last step we used $(\iota_{\hat{A}} * \alpha_3) \wedge * \alpha_3 = 0$. Therefore, the Kähler potential does not depend on A_6 and A_4 , in agreement with $E_{7(7)}$ invariance. Note that this expression reduces to the known one in the G_2 -structure case.

As has been derived in [3], the superpotential W is given through the eigenvalue equation

$$(D\phi) \cdot \phi = (e^{K_\phi/2} W) \phi , \quad (3.54)$$

where D is defined in (3.38). We present the detailed computation of the superpotential in Appendix B.1. We get

$$e^{K_\phi/2} W = \iota_{\rho_8} \phi_4^{(0)} \wedge d\phi_4^{(0)} + \rho_8 \wedge dA_6 - 2i \phi_4 \wedge \iota_{\rho_8} dA_4 + \iota_{\rho_8} A_4 \wedge dA_4 . \quad (3.55)$$

which is exactly the result of [3]. A similar result for manifolds of G_2 structure has been obtained in [10].

3.4 $N = 2$ in the language of $N = 1$

To finish this section, we note that the $SU(6)$ structure of $N = 2$ reductions can also be understood as a triple of $SU(7)$ structures, by using the product $\mathbf{133} \times \mathbf{56} \rightarrow \mathbf{912}$ given in (A.10). We find the objects

$$\begin{aligned} \hat{\phi}_a^{(0)} &= \hat{L}^{(0)} \otimes K_a^{(0)} = 2\kappa(\epsilon_{ik}(\sigma_a)^k{}_j \eta_i \otimes \eta_j, 0, \epsilon_{ik}(\sigma_a)^k{}_j \bar{\eta}_i \otimes \bar{\eta}_j, 0) , \\ \tilde{\phi}_a^{(0)} &= \tilde{L}^{(0)} \otimes K_a^{(0)} = 2\kappa(-i \epsilon_{ik}(\sigma_a)^k{}_j \eta_i \otimes \eta_j, 0, i \epsilon_{ik}(\sigma_a)^k{}_j \bar{\eta}_i \otimes \bar{\eta}_j, 0) , \end{aligned} \quad (3.56)$$

which are non-zero and define an $SU(2)$ triplet of $SU(7)$ structures of the form given in (3.40). The index a here labels the various symmetric combinations of the η_i . A spinor

$\eta = \alpha_i \eta_i$ corresponds then to the $SU(7)$ structure defined by $\phi = (\alpha_i \epsilon_{ik} (\sigma_a)^k_j \alpha_j) \phi_a$, where $\phi_a^{(0)} = \hat{\phi}_a^{(0)} + i \tilde{\phi}_a^{(0)}$.

For an $SU(6)$ structure the $\phi_a^{(0)}$ can be computed in terms of the $SU(4)$ forms J_8 and Ω_4 on the 8-dimensional bundle. For this, we use (3.29) and (3.31). In terms of the decomposition (2.3), we then find

$$\begin{aligned} \phi_1^{(0)} &= -2e^{-K_L/2} (0, i g_8^{(0)} \cdot (\text{vol}_8^{-1} \lrcorner \text{Re } \Omega_4^{(0)}), 0, (g_8^{(0)})^{-1} \cdot \text{Re } \Omega_4^{(0)}), \\ \phi_2^{(0)} &= -2e^{-K_L/2} \kappa((g_8^{(0)})^{-1}, e^{K_L} g_8^{(0)} \cdot (\text{vol}_8^{-1} \lrcorner (J_8^{(0)} \wedge J_8^{(0)})), \\ &\quad i g_8^{(0)}, i e^{K_L} (g_8^{(0)})^{-1} \cdot (J_8^{(0)} \wedge J_8^{(0)})), \\ \phi_3^{(0)} &= -2e^{-K_L/2} (0, -i g_8^{(0)} \cdot (\text{vol}_8^{-1} \lrcorner \text{Im } \Omega_4^{(0)}), 0, (g_8^{(0)})^{-1} \cdot \text{Im } \Omega_4^{(0)}), \end{aligned} \tag{3.57}$$

where $g_8^{(0)}$ is given in (3.30). As before, the general form of ϕ_a is obtained by acting with A_6 and A_3 on the above expressions. The action of A_6 turns $g_8^{(0)}$ into g_8 (cf. Eq. (3.47)), $J_8^{(0)}$ into J_8 and $\Omega_4^{(0)}$ into Ω_4 (see (3.34)), while A_3 acts as usual by the 4-form shift $e^{\rho_8 \wedge A_3}$.

One can therefore understand the $SU(6)$ structure in E_7 relevant for $N = 2$ compactifications as a triple of $SU(7)$ structures. When we perform a projection on the $SU(6)$ structure, for instance by orbifolding or orientifolding, a single combination of these $SU(7)$ structures will survive, giving the $N = 1$ description one expects. We will discuss such projections in Section 5.

4 Type IIA reductions

4.1 Type IIA and $GL(6)$ decompositions

To descend to type IIA, we further split the 7-dimensional tangent space into six plus one-dimensional pieces, i.e.

$$\begin{aligned} T_7^* &= T_6^* \oplus T_y^* \\ \rho_m &= (\rho_{\hat{m}}, \rho_y) \end{aligned} \tag{4.1}$$

Choosing T_y to have no $GL(6)$ weight, we get that the exceptional tangent bundle (2.5) decomposes as $\mathbf{56} = \mathbf{6} \oplus \mathbf{6} \oplus \mathbf{6} \oplus \mathbf{6} \oplus \mathbf{32}$, i.e.

$$\begin{aligned} E_{\text{IIA}} &= (\Lambda^6 T_6)^{1/2} \otimes ((T_6 \oplus \Lambda_0 T_6^* \oplus \Lambda^2 T_6^* \oplus T_6^* \oplus \Lambda^5 T_6^* \oplus \Lambda^4 T_6^* \oplus (T_6^* \otimes \Lambda^6 T^*) \oplus \Lambda^6 T^*) \\ &= (\Lambda^6 T_6)^{1/2} \otimes ((T_6 \oplus T_6^* \oplus \Lambda^5 T_6^* \oplus (T_6^* \otimes \Lambda^6 T^*) \oplus \Lambda^{\text{even}} T_6^*) , \end{aligned} \tag{4.2}$$

where from the last expression we recognize the type IIA charges, namely momentum, winding, their magnetic duals and the p-brane charges.

The adjoint decomposes as

$$\begin{aligned}
A_{\text{IIA}} = & [\lambda \oplus (T_6 \otimes T_6^*)_0 \oplus (T_y \otimes \Lambda^2 T_6) \oplus (T_y^* \otimes \Lambda^2 T_6^*)] \oplus [\varphi \oplus \Lambda^6 T_6 \oplus \Lambda^6 T_6^*] \\
& \oplus [(T_y \otimes T_6^* \oplus \Lambda^3 T_6^* \oplus (T_y^* \otimes \Lambda^5 T_6^*)) \oplus [(T_y^* \otimes T_6 \oplus \Lambda^3 T_6 \oplus (T_y \otimes \Lambda^5 T_6))] \quad (4.3) \\
= & (T_6 \otimes T_6^*) \oplus \Lambda^2 T_6 \oplus \Lambda^2 T_6^* \oplus \mathbb{R} \oplus \Lambda^6 T_6^* \oplus \Lambda^6 T_6 \oplus \Lambda^{\text{odd}} T_6^* \oplus \Lambda^{\text{odd}} T_6
\end{aligned}$$

where

$$\lambda = dy \otimes \partial_y, \quad \varphi = 2dy \otimes \partial_y + dx^{\hat{m}} \otimes \partial_{\hat{m}}, \quad (4.4)$$

are linear combinations of the generators for shifts in the volumes of the six-dimensional part and the eleventh dimension. From the last equality we recognize the $O(6,6)$ adjoint, where the $GL(6)$ and B_2 -field transformations live, the $SL(2)$ adjoint where the dual B_6 of B_2 is, and the sum of odd forms corresponding to the shifts of the RR potentials.

More precisely, under the breaking of the U-duality group $E_{7(7)}$ into the product of T-duality and S-duality group $SO(6,6) \times SL(2)$, the fundamental representation splits according to¹⁰

$$\begin{aligned}
\mathbf{56} &= (\mathbf{12}, \mathbf{2}) \oplus (\mathbf{32}, \mathbf{1}), \\
L^A &= (L^{Ai}, L^\pm)
\end{aligned} \quad (4.5)$$

where $A = 1, \dots, 12$ ($i = 1, 2$) is a fundamental $O(6,6)$ ($SL(2)$) index, and $\pm$ represents a positive or negative chirality $O(6,6)$ spinor (the plus is relevant for type IIA and M-theory, while for type IIB we need the negative chirality representation). The adjoint decomposes as the adjoint of each group, plus a spinor contribution

$$\begin{aligned}
\mathbf{133} &= (\mathbf{66}, \mathbf{1}) \oplus (\mathbf{1}, \mathbf{3}) \oplus (\mathbf{32}', \mathbf{2}), \\
K &= (K^A_B, K^i_j, K^{\mp i}).
\end{aligned} \quad (4.6)$$

The embedding of the gauge fields B_2, B_6 and $C^\mp$ (that we will call collectively A_{shifts}) in type IIA and type IIB is the following [4]

$$A_{\text{shifts}} = \left(\begin{pmatrix} 0 & B_2 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & B_6 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} C^\mp \\ 0 \end{pmatrix} \right). \quad (4.7)$$

We can now write explicitly the one-form v and gauge fields A_3 (or A_4), A_6 of the previous sections in terms of their type IIA counterparts

$$v^{(0)} = dy + C_1, \quad C_5 = \iota_{\partial_y} A_6, \quad A_4 = \rho_8 \wedge (C_3 - dy \wedge B_2), \quad \iota_{\partial_y} C_3 = 0. \quad (4.8)$$

Inspecting (2.7), we can write the $E_{7(7)}$ embedding of the gauge fields in $SL(8, \mathbb{R})$ decomposition (cf. (2.2)) as follows

$$A_{\text{shifts}} = (C_1 \otimes \partial_y + \rho_8 \otimes \hat{C}_5, \rho_8 \wedge C_3 - \rho_8 \wedge dy \wedge B) \quad (4.9)$$

where $\hat{C}_5$ is the vector associated to C_5 , i.e.

$$\hat{C}_5 = \text{vol}_6^{-1} \cdot C_5. \quad (4.10)$$

¹⁰S-duality here does not refer to the type IIB S-duality, but as the group that acts by fractional linear transformations on $\tau = B_6 + i e^{-\phi}$.

4.2 $N = 2$ and $N = 1$ reductions

As in M-theory, reductions to 4D with $N = n$ supersymmetry require n internal $SU(8)$ spinors η^i , which show up in the decomposition of the two ten-dimensional spinors $\epsilon^{1,2}$ as follows

$$\begin{pmatrix} \epsilon^1 \\ \epsilon^2 \end{pmatrix} = \xi_-^i \otimes \eta_i + \text{c.c.} \quad (4.11)$$

where η_i are $SU(8)$ spinors that combine the $SU(4) \cong O(6)$ spinors that build up ϵ_1 and ϵ_2 .

Given $\eta_{1,2}$ and η for the case of $N = 2$ and $N = 1$, the reductions work exactly as in M-theory, namely one builds the structures $L^{(0)}, K_a^{(0)}$ as in (3.4), (3.6) in the case of $N = 2$ [4], and $\phi^{(0)}$ as in (3.40) in the case of $N = 1$. Their full orbit is obtained by the $E_{7(7)}$ action of the gauge fields (4.9).

Let us concentrate on the $N = 2$ case now. The form of L resembles very much the pure spinor counterpart e^{B+iJ} for an $SU(3)$ structure. Indeed, we get

$$L = e^{(C_1 \otimes \partial_y + \rho_8 \otimes \hat{C}_5, \rho_8 \wedge C_3)} e^{\rho_8 \wedge dy \wedge (-B - iJ)} \cdot (\hat{\rho}_8 \wedge \hat{v}, 0) . \quad (4.12)$$

Note however that J here is a 2-form constructed as a bilinear of two different $SU(8)$ spinors, and furthermore it is complex. To make the comparison with GCG more straightforward, one can parameterize them as¹¹

$$\eta_1 = \begin{pmatrix} \theta_+^1 \\ \tilde{\theta}_-^1 \end{pmatrix}, \quad \eta_2 = \begin{pmatrix} \tilde{\theta}_+^2 \\ \theta_-^2 \end{pmatrix} . \quad (4.13)$$

For the special ansatz $\tilde{\theta}^i = 0$, L and K have particularly nice forms in terms of the $O(6,6)$ pure spinors¹²

$$\Phi^\pm = e^B (\theta_+^1 \otimes \tilde{\theta}_\pm^2) \quad (4.14)$$

the $SL(2, \mathbb{R})$ vielbein u^i related to the four-dimensional axiodilaton, $i = 1, 2$, and the RR-spinor $C = C_1 + C_3 + C_5$ as [4]

$$L = e^C (0, \Phi^+) , \quad K_3 + i K_1 = e^C (0, 0, u^i \Phi^-) , \quad (4.15)$$

where this is written in the $O(6,6) \times SL(2, \mathbb{R})$ decomposition of $E_{7(7)}$, given explicitly below in (4.5), (4.6), and K_2 is just the commutator of K_3 and K_1 .

5 From $N = 2$ to $N = 1$: Orientifolding and orbifolding in EGG

As we will show in detail in Section 5.2.4, orientifolds break the $E_{7(7)}$ covariance into that of the subgroup $O(6,6) \times SL(2, \mathbb{R})_O$, where the “ O ” makes it explicit that this is a different subgroup from that of T and S -duality. Furthermore, as we will see, each orientifold projection gives rise to a different $O(6,6) \times SL(2, \mathbb{R})$ subgroup. The splitting of the fundamental and adjoint representations of $E_{7(7)}$ has been given in (4.5) and (4.6).

¹¹In standard Calabi-Yau compactifications, one takes $\theta^1 = \theta^2 = \theta$, $\tilde{\theta}^i = 0$. Note that in this case η_i as defined in (4.13) are not Majorana, but the combinations $\eta_1 + \eta_2$ and $i(\eta_1 - \eta_2)$ are.

¹²Note that for this ansatz, $J(\Omega)$ contains the bilinears between the two θ 's involving two (three) Spin(6) gamma matrices.

5.1 Orbifold action on T_8 and its reduction to M-theory

The M-theory uplift of type IIA O6-orientifolds are a geometric involution on the 7-dimensional space. Such an involution can in turn be uplifted to an orbifold action $\tilde{\sigma}^*$ on the 8-dimensional space T_8 such that the $SL(8)$ bundle decomposes at the locus of the action into a positive and a negative eigenbundle

$$T_8 = T_8^+ \oplus T_8^- , \quad (5.1)$$

and such that both subspaces are four-dimensional. The adjoint of $E_{7(7)}$ (2.2) decomposes under (5.1) as

$$\begin{aligned} E = & (T_8^+ \otimes T_8^{*+})_0 \oplus (T_8^- \otimes T_8^{*-})_0 \oplus (\Lambda^2 T_8^{*+} \otimes \Lambda^2 T_8^{*-}) \oplus T_0 \oplus \Lambda^4 T_8^{*+} \oplus \Lambda^4 T_8^{*-} \\ & \oplus (T_8^+ \otimes T_8^{*-}) \oplus (T_8^- \otimes T_8^{*+}) \oplus (\Lambda^3 T_8^{*+} \otimes \Lambda^1 T_8^{*-}) \oplus (\Lambda^1 T_8^{*+} \otimes \Lambda^3 T_8^{*-}) , \end{aligned} \quad (5.2)$$

where T_0 is the element of the adjoint that acts as ± 1 on $T_8^\pm$. By comparing to (4.6), we can see how E_7 is broken into $O(6,6) \times SL(2, \mathbb{R})$: the first line builds up the adjoint of $O(6,6) \times SL(2, \mathbb{R})_O$, which is even under the orbifold action, while the terms in the second line are odd and form the **(2, 32')** representation. Similarly, the fundamental of $E_{7(7)}$, given in (2.1) in terms of $SL(8)$ representations, decomposes as

$$A = \Lambda^2 T_8^+ \oplus \Lambda^2 T_8^- \oplus \Lambda^2 T_8^{*+} \oplus \Lambda^2 T_8^{*-} \oplus (T_8^+ \otimes T_8^-) \oplus (T_8^{*-} \otimes T_8^{*-}) , \quad (5.3)$$

where the first four terms are even and form the **(12, 2)** representation of $O(6,6) \times SL(2, \mathbb{R})_O$ (see Eq. (4.5)), while the last two, odd terms, form the **(32, 1)**.

To descend to M-theory, we require the orbifold action to have positive eigenvalue when acting on $\hat{\rho}_8$. Eq. (2.4) tells us then that T_7^+ is three-dimensional, while T_7^- is four-dimensional. Finally, to recover the type IIA orbifold action that gives rise to O6 planes, we require $\hat{v}$ to have negative eigenvalue. In summary

$$T_8 = T_8^+ \oplus T_8^- = (T_7^+ \oplus T_{\hat{\rho}_8}^+) \oplus T_7^- = (T_6^+ \oplus T_{\hat{\rho}_8}^+) \oplus (T_6^- \oplus T_y^-) . \quad (5.4)$$

We will come back to the full orientifold projection later in Section 5.2.1

Now let us see how the orbifold acts on the $N = 2$ structures defined in the previous sections. In type IIA, an involutive symmetry σ that can be used to mod out the theory should be anti-holomorphic if $N = 1$ supersymmetry is to be preserved [11]. This means that for an $SU(3)$ structure defined by J and Ω , it should act as $\sigma^* J = -J$, $\sigma^* \Omega = \bar{\Omega}$. This is easy to uplift to an action on J_8 , Ω_4 defining the $SU(4)$ structure on T_8 , namely we require σ to act as

$$\tilde{\sigma}^* J_8 = -J_8 , \quad \tilde{\sigma}^* \Omega_4 = -\bar{\Omega}_4 . \quad (5.5)$$

This implies that the action induced by $\tilde{\sigma}^*$ on K_a and L in the **133** and the **56** representation, which define an $SU(6) \subset E_7$ structure, should be

$$\tilde{\sigma}^* L = -L , \quad \tilde{\sigma}^* K_1 = K_1 , \quad \tilde{\sigma}^* K_{2/3} = -K_{2/3} . \quad (5.6)$$

Therefore, L and $K_{2/3}$ are not well-defined any more in the presence of fixed points. However, their products are well-defined under the orbifold action. More precisely, their

product in the **912** representation is defined by¹³

$$L \otimes (K_2 + \mathbf{i} K_3) = \sqrt{\kappa} \phi , \quad (5.7)$$

where the pre-factor $\sqrt{\kappa}$ appears due to the different normalizations in (3.2) and (3.41). This ϕ in the **912** defines in turn an $SU(7)$ structure following Section 3.3, corresponding to the single spinor that survives the orbifolding. ϕ defines the metric g and a four-form ϕ_4 , cf. (3.46). From (5.7) we find

$$\begin{aligned} \phi_4 &= \sqrt{\kappa}^{-1} e^{-K_L/2} \text{Im } \Omega_4 + \sqrt{\kappa} e^{K_L/2} J_8 \wedge J_8 \\ \phi_4^r &= e^{-K_L} \text{Im } \Omega_4 + \kappa J_8 \wedge J_8 . \end{aligned} \quad (5.8)$$

We find the second expression using $c = \sqrt{\kappa} e^{-K_L/2}$.

The orbifold projection selects an $N = 1$ special Kähler subspace inside the $N = 2$ Kähler and quaternionic spaces. The generator of its complex structure is given in (3.50), which can in turn be written in terms of the $SU(4)$ -structure objects J_8 and Ω_4 in L and K respectively as

$$\mathcal{J}_\phi = e^{A_4} \cdot (0, e^{-K_L} \text{Im } \Omega_4 + \kappa J_8 \wedge J_8) = e^{-K_L} K_1 + \kappa \mathcal{J}_L . \quad (5.9)$$

Therefore, the complex structure on the $N = 1$ Kähler space $e^{\mathcal{J}_\phi}$ is the tensor product of the complex structures e^{K_1} with $e^{\mathcal{J}_L}$. If the orbifold singularities were blown-up (see comments below), $e^{\mathcal{J}_\phi}$ would not be block-diagonal any more. As long as the singularities are not blown up, the Kähler potential (3.53) simplifies to the sum the two Kähler potentials for L and K , i.e.

$$K_\phi = -\frac{1}{2} \log \kappa + K_L + \frac{1}{2} \log 2 , \quad (5.10)$$

The superpotential is given in (3.55). On the other hand, we have the Killing prepotentials (3.39) that should descend to the $N = 1$ description. Comparing both expressions we find the relation

$$e^{K_\phi/2} W = \frac{1}{2} \kappa^{-1} (P^2 + \mathbf{i} P^3) . \quad (5.11)$$

The above formulas are valid for the orbifold of an $SU(6)$ structure. If we blow-up the singularities resulting from the orbifolding, we switch on additional modes in ϕ that alter its form from the one given in (5.7). More precisely, the objects $K_{2/3}$ and L are not well-defined on the blown-up manifold, while ϕ still defines the geometry. The blow-up should lead to new modes that enter ϕ_4 as extra four-forms.

5.2 Further descent to type IIA

5.2.1 O6 orientifolds

To recover O6-orientifolds, the orbifold involution $\tilde{\sigma}$ should have negative eigenvalue on T_y , i.e. act on T_7 as $\text{diag}(\sigma, -1)$ where σ is an involution on the 6-dimensional space

¹³Note that the **56** component of their tensor product is forced to be zero by the compatibility condition.

whose action is given above (5.5). Furthermore, the O6 projection mods out by the action of $\sigma\Omega_p(-1)^{F_L}$, where Ω_p is the worldsheet parity, and $(-1)^{F_L}$ gives an additional minus sign on the RR sector. The uplift of this combination is the purely geometric involution $\tilde{\sigma}$.

The combined operation $\Omega_p(-1)^{F_L}$ has a different action on the different $O(6,6) \times SL(2, \mathbb{R})$ components of L and K_a . On $O(6,6)$ bispinors, such as the RR potentials or the pure spinors of generalized complex geometry $\Phi^\pm$, which are tensor products of a left and a right-moving spinor, it acts in the following way [12]

$$(-1)^{F_L}\Omega_p\Phi^+ = \lambda(\Phi^+) , \quad (-1)^{F_L}\Omega_p\Phi^- = -\lambda(\bar{\Phi}^-) , \quad (-1)^{F_L}\Omega_p C = \lambda(C) \quad (5.12)$$

where λ is the following action on forms

$$\lambda(\alpha_{2p}) = (-1)^p \alpha_{2p} , \quad \lambda(\alpha_{2p-1}) = (-1)^p \alpha_{2p-1} . \quad (5.13)$$

This can be understood since worldsheet parity exchanges the left and right-moving sectors, and on the bispinors, which are tensor products of left and right moving spinors, it acts by transposition. Since the orientifold projection keeps states which are even under the action of $\sigma(-1)^{F_L}\Omega_p$, one requires the involution to satisfy

$$\sigma^*\Phi^+ = \lambda(\Phi^+) , \quad \sigma^*\Phi^- = -\lambda(\bar{\Phi}^-) , \quad \sigma^*C = \lambda(C) . \quad (5.14)$$

We want to define an analogous “ λ -operation” as an action on fundamental $SL(2)$ and $O(6,6)$ indices. The following operator acting respectively on the **12** of $O(6,6)$, **2** of $SL(2, \mathbb{R})$ and **32** of $O(6,6)$ does the job

$$\tilde{\lambda} = \begin{pmatrix} 1_{6 \times 6} & 0 \\ 0 & -1_{6 \times 6} \end{pmatrix} \otimes \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \otimes (-\lambda). \quad (5.15)$$

For higher representations $\tilde{\lambda}$ just acts on all indices.¹⁴ Therefore, on the fundamental **56** representation, which decomposes into $O(6,6) \times SL(2, \mathbb{R})$ as in (4.5), this action reads

$$\tilde{\lambda}(L) = \left(\begin{pmatrix} L^{\hat{m}1} & -L_{\hat{m}}^1 \\ -L^{\hat{m}2} & L_{\hat{m}}^2 \end{pmatrix}, -\lambda(L^+) \right) . \quad (5.16)$$

On the adjoint representation, whose $O(6,6) \times SL(2, \mathbb{R})$ decomposition is given in (4.6), we get

$$\tilde{\lambda}(K) = \left(\begin{pmatrix} K^{\hat{m}}_{\hat{n}} & -K^{\hat{m}\hat{n}} \\ -K_{\hat{m}\hat{n}} & K_{\hat{m}}^{\hat{n}} \end{pmatrix}, \begin{pmatrix} K^1_1 & -K^1_2 \\ -K^2_1 & K^2_2 \end{pmatrix}, \begin{pmatrix} -\lambda(K^{-1}) \\ \lambda(K^{-2}) \end{pmatrix} \right) \quad (5.17)$$

(where by construction $K^2_2 = -K^1_1$ and $K_{\hat{m}}^{\hat{n}} = -K^{\hat{m}}_{\hat{n}}$).

The claim is that $\tilde{\lambda}$ acts like $\Omega_p(-1)^{F_L}$ on K_1 , while on L and $K_{2/3}$ it is $-\tilde{\lambda}$ that does the job. The fields that will survive the orientifold projection are therefore those for which σ acts in the following way

$$\sigma^*L = -\tilde{\lambda}(L) , \quad \sigma^*K_1 = \tilde{\lambda}(K_1) , \quad \sigma^*K_{2/3} = -\tilde{\lambda}(K_{2/3}) . \quad (5.18)$$

¹⁴Note that the action on $T \oplus T^*$ then induces the action λ in (5.13) on the spinor representation (isomorphic to a sum of forms).

In the language of (4.13), we see from (3.4)-(3.6) that the action of $\tilde{\lambda}$ corresponds to the exchange of the two spinors η^i .

For the corresponding vector fields $L_\mu = (L_\mu^{iA}, L_\mu^+)$ in the **56** representation we have

$$\sigma^* L_\mu = \tilde{\lambda}(L_\mu) . \quad (5.19)$$

Here, L_μ^{Ai} are the electric and dual magnetic vectors coming from the off-diagonal components for the metric and the B-field, while L_μ^+ collects the Ramond-Ramond fields with one external leg, i.e. $L_\mu^+ = (C_1)_\mu + (C_3)_\mu + (C_5)_\mu + (C_7)_\mu$.

5.2.2 Type IIB orientifolds

For completeness (and because we will use later O9 as an illustration) we give the action for type IIB orientifolds.¹⁵ There, the theory is modded out by $\sigma\Omega_p(-1)^{F_L}$ for O3/O7 projection, and $\sigma\Omega_p$ for O5/O9. This means that the latter projection has an extra minus sign on the $O(6,6)$ spinors with respect to the type IIA case, i.e. we define

$$\tilde{\lambda}_{\text{IIB}} = \begin{pmatrix} 1_{6 \times 6} & 0 \\ 0 & -1_{6 \times 6} \end{pmatrix} \otimes \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \otimes \pm \lambda, \quad (5.20)$$

where the plus sign is for O3/O7 projections, while the minus applies to O5/O9. This contributes to a $\pm$ sign in the last components of (5.16) and (5.17). We then require (5.18) and (5.19), with $\tilde{\lambda}$ replaced by $\tilde{\lambda}_{\text{IIB}}$.

5.2.3 New Z_2 projections

In general, new orientifold actions can be found by conjugating known orientifold actions with elements in $E_{7(7)}(\mathbb{Z})$. For all these new orientifolds our discussion applies. A simple example of a new Z_2 action is the NS5-projection that is related to O5-orientifolding in type IIB by S-duality in ten dimensions. Concerning the involution, S-duality only exchanges the roles of the B field and the field C_2 . Therefore, the NS-NS (R-R) sector is even (odd) under the resulting involution, which thus can be written as $(-1)^{F_L}\sigma$, where F_L is the left-moving fermion number on the world-sheet and σ is an involution of the internal space that inverts four of the internal directions, satisfying the following on the pure spinors of GCG and the RR fields

$$\sigma^* \Phi^\pm = \Phi^\pm, \quad \sigma^* C = -C . \quad (5.21)$$

Correspondingly, the involution $\tilde{\lambda}_{\text{NS5}}$ is

$$\tilde{\lambda}_{\text{NS5}} = 1_{12 \times 12} \otimes 1_{2 \times 2} \otimes (-1)_{\mathbf{32}} . \quad (5.22)$$

Subsequently, the roles of K_1 and K_3 are exchanged with respect to (5.6). S-duality implies that the fixed points of this action are negative tension objects with negative NS5-brane charge.

¹⁵Note that in type IIB the roles of Φ^+ and Φ^- are exchanged.

Note that this action can be defined in a completely analogous way in type IIA, and it can be uplifted to M-theory to find the orientifolding for M5-branes, with

$$\tilde{\sigma}_{\text{M5}}^* dy = -dy , \quad \tilde{\sigma}_{\text{M5}}^* \rho_8 = -\rho_8 . \quad (5.23)$$

The analogous D4-orientifolding lifts to the same expression, but without any involution of dy . Though we can uplift these involutions to M-theory, even with these assignments for $\tilde{\sigma}_{\text{M5}}$, the M5-involution does not become an orbifold action. More precisely, it acts on the adjoint representation as σ_{M5}^* but on the exceptional generalized tangent bundle with an extra minus sign, i.e. with $-\sigma_{\text{M5}}^*$. Therefore, the projection on L and K_a is given by

$$\tilde{\sigma}_{\text{M5}}^* L = L , \quad \tilde{\sigma}_{\text{M5}}^* K_1 = K_1 , \quad \tilde{\sigma}_{\text{M5}}^* K_{2/3} = -K_{2/3} , \quad (5.24)$$

in contrast to the orbifold action given in (5.6). Thus, no $SU(7)$ structure surviving the involution can be defined. As a consequence the fixed points of σ_{M5} cannot be resolved in a geometric way within M-theory, in contrast to the orbifold fixed points of Section 5.1.

5.2.4 Kähler subspaces

Here we show how the orientifold projection selects the $N = 1$ special Kähler subspaces inside the $N = 2$ Kähler and quaternionic ones. Before we analyze how a Kähler space emerges from the projection on the hypermultiplets, we first want to understand the reduction of $E_{7(7)}$ under the orientifolding. Let us first start with an orientifolding to O9-planes, i.e. σ is the identity (and we are modding out the theory just by the action of Ω_p). As the representations of $E_{7(7)}$ split into the even and odd parts under $\tilde{\lambda}$, they form representations of a subgroup of $E_{7(7)}$ that is the subgroup of even transformations. Therefore, we analyze the action of $\tilde{\lambda}$ on the adjoint of $E_{7(7)}$, split into representations of the subgroup $O(6, 6) \times SL(2, \mathbb{R})$ corresponding to T- and S-duality subgroups, cf. Eq. (4.6).¹⁶

On the adjoint of $O(6, 6)$, $\tilde{\lambda}$ acts as in the first component of (5.17). The **66** representation therefore gets projected to

$$\mathbf{66} \rightarrow \mathbf{35_0} \oplus \mathbf{1_0} , \quad (5.25)$$

$$\mu^A_B \rightarrow \mu^{\hat{m}}_{\hat{n}}$$

Thus we find $O(6, 6) \rightarrow Gl(6, \mathbb{R}) = SL(6, \mathbb{R}) \times \mathbb{R}_+$ (and the subindex denotes the charge under this $\mathbb{R}_+$, corresponding to the volume). Similarly

$$\mathbf{3} \rightarrow \mathbf{1_0} , \quad (5.26)$$

$$\mu^i_j \rightarrow \mu^1_1$$

and thus $SL(2, \mathbb{R}) \rightarrow \mathbb{R}_+$ (and the subindex denotes the charge under this $\mathbb{R}$, corresponding to the dilaton). Finally, on the $(\mathbf{32'}, \mathbf{2})$ representation we get (recall that for O9, $\tilde{\lambda}_{\text{IIB}}$ acts as $-\lambda$ on the spinor)

$$(\mathbf{32'}, \mathbf{2}) \rightarrow \mathbf{1}_{(+1, +1)} \oplus \mathbf{15}_{(+1, -1)} \oplus \mathbf{1}_{(-1, -1)} \oplus \mathbf{15}'_{(-1, +1)} , \quad (5.27)$$

$$\mu^{+i} \rightarrow \mu^2_{(0)} + \mu^1_{(2)} + \mu^1_{(6)} + \mu^2_{(4)} .$$

¹⁶Here S-duality does not refer to the type IIB S-duality acting on the RR axion C_0 and the dilaton, but the S-duality within the NS sector, that acts on $\tau = B_6 + i e^{-\phi}$.

On the first line we stated the $SL(6, \mathbb{R})$ representations and denoted the charges under the two R_+ factors coming from the volume and the dilaton, and on the second line the superscript denotes the $SL(2)$ component, while the number in parenthesis in the subscript denotes the degree of the form.

We see that the diagonal R_+ factor together with the two scalars in (5.27) forms an $SL(2, \mathbb{R})$ group, while the two **15**s together with the non-diagonal R_+ factor enhance the $SL(6, \mathbb{R})$ to $O(6, 6)$. Thus, the new covariance group is $O(6, 6) \times SL(2, \mathbb{R})$. Since this is a different $O(6, 6) \times SL(2, \mathbb{R})$ from the original one associated with S- and T-duality (see Footnote 16), we call this $O(6, 6) \times SL(2, \mathbb{R})_O$. Thus we get

$$E_7 \rightarrow O(6, 6) \times SL(2, \mathbb{R})_{O_9} ,$$

$$\mu \rightarrow \left(\left(\begin{pmatrix} \mu^{\hat{m}}_{\hat{n}} & \mu^1_{(2)} \\ \mu^2_{(4)} & \mu^{\hat{m}}_{\hat{n}} \end{pmatrix}, \begin{pmatrix} \mu^1_1 & \mu^1_{(6)} \\ \mu^2_{(0)} & -\mu^1_1 \end{pmatrix}, 0 \right) , \right.$$

$$A_{\text{shifts}} \rightarrow \left(\left(\begin{pmatrix} 0 & C_2 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & C_6 \\ 0 & 0 \end{pmatrix}, 0 \right)$$

where in the last line we have used the $O(6, 6) \times SL(2, \mathbb{R})$ embedding of the B and C -fields given in (4.7).

If σ is not the identity, the situation is slightly more involved. The orientifolding in general maps different points onto each other. Only at the locus of the O-planes the covariance group can be really projected to a subgroup. Let us consider the case of an $O(3 + p)$ -plane. At the $O(3 + p)$ -plane we can split the tangent space

$$T \rightarrow T_{\parallel}^{(p)} \oplus T_{\perp}^{(6-p)} , \quad (5.28)$$

where the supraindex in parenthesis indicates the dimensions of each space. The involution σ^* acts as $+1$ on $T_{\parallel}$ and as -1 on $T_{\perp}$. Therefore, the combination $\sigma^* \tilde{\lambda}$ projects the geometric group

$$Gl(6, \mathbb{R}) \rightarrow Gl_{\parallel}(p, \mathbb{R}) \times Gl_{\perp}(6 - p, \mathbb{R}) . \quad (5.29)$$

Furthermore, $\sigma^* \tilde{\lambda}$ projects

$$\Lambda^2 T^* \rightarrow T_{\parallel}^* \otimes T_{\perp}^* , \quad \Lambda^2 T \rightarrow T_{\parallel} \otimes T_{\perp} , \quad (5.30)$$

and these give each the $(\mathbf{p}, \mathbf{6} - \mathbf{p})$ representations that enhance $Gl_{\parallel}(p, \mathbb{R}) \times Gl_{\perp}(6 - p, \mathbb{R})$ to $Gl(6, \mathbb{R})_{O(3+p)}$. Thus, as for the case of O9-planes, we find $O(6, 6) \rightarrow Gl(6, \mathbb{R})$, but now to a different $Gl(6, \mathbb{R})$ indicated by the subindex. Under the breaking $O(6, 6) \rightarrow Gl(6, \mathbb{R})_{O(3+p)}$, the $(\mathbf{2}, \mathbf{32}')$ representation projects as in (5.27). Here, the two surviving singlets are $\Lambda^p T_{\parallel}^*$ and $\Lambda^{(6-p)} T_{\perp}^*$, which form singlets under the emerging $Gl(6, \mathbb{R})_{O(3+p)}$. Hence, we see that for all orientifold actions, the covariance group projects to $O(6, 6) \times SL(2, \mathbb{R})_{O(p+3)}$ (as we saw this subgroup is different for each type of orientifold).

Now let us consider the projection (5.18) on the vector and hypermultiplet sectors. The vector fields that survive the orientifold projection are those that are even under $\sigma^* \tilde{\lambda}$ (see (5.19)). For O9, where σ is the identity and $\tilde{\lambda}$ acts as $-\lambda$ in the spinor part, we get that the surviving vector fields are the Kaluza-Klein vectors as well as the vectors associated with the internal one-form $(C_2)_{\mu}$ (and their magnetic duals). As for the $N = 1$

chiral fields that descend from $N = 2$ vector multiplets, we keep from L only the pieces that are invariant under $-\sigma^*\tilde{\lambda}$. Again, for an O9 and an $SU(3)$ structure, we have that the projection onto states that are invariant under $\tilde{\lambda}$ gives that all degrees of freedom in the three-form Ω is kept.

In the hypermultiplet sector, since $E_{7(7)}$ is projected onto $O(6,6) \times SL(2, \mathbb{R})_{O(p+3)}$, we know from (5.18) that both K_2 and K_3 will be in the $(\mathbf{32}', \mathbf{2})$ representation of $O(6,6) \times SL(2, \mathbb{R})_{O(p+3)}$, which is odd under the projection. Since $[K_2, K_3] \sim K_1$ and each K_2 and K_3 determine each other, $K_2 + iK_3$ defines a pure $O(6,6)$ spinor tensored with a doublet of $SL(2, \mathbb{R})$. Therefore, $K_2 + iK_3$ parametrizes a special Kähler space. On the other hand, K_1 is in the $(\mathbf{66}, \mathbf{1}) \oplus (\mathbf{1}, \mathbf{3})$ of $O(6,6) \times SL(2, \mathbb{R})_{O(p+3)}$. It can be understood as a generalized almost complex structure on the orbit of $K_2 + iK_3$.

6 Discussion

In this work we derived the form of the couplings for general $SU(7)$ and $SU(6)$ structures in M-theory and type IIA, which correspond to (off-shell) $N = 1$ and $N = 2$ supersymmetric compactifications to four dimensions, building on and extending the work of [3, 4]. Using EGG we could reformulate all degrees of freedom in such backgrounds by a set of fundamental objects in $E_{7(7)}$ representations. Moreover, the effective couplings are easily determined as singlets that are tensor products of the fundamental objects and their first derivatives in $E_{7(7)}$. In particular, $N = 1$ backgrounds are determined by an $SU(7)$ structure ϕ in the $\mathbf{912}$ representation. Its quartic invariant gives the Kähler potential, while the superpotential is determined by an eigenvalue equation. In contrast, $N = 2$ backgrounds admit two sectors: vector- and hyper-multiplets. The former is described by one object L in the (fundamental) $\mathbf{56}$ representation whose quartic invariant gives the Kähler potential. The hypermultiplets are described by an $SU(2)$ subalgebra spanned by a triplet of structures K_a in the adjoint representation. The normalization of the $SU(2)$ commutator relations gives the hyper-Kähler potential of the hyper-Kähler cone over this quaternionic Kähler space. L and K_a together define an $SU(6)$ structure. The couplings of the two sectors, i.e. the prepotentials, are given by a triple tensor product of these two objects with the derivative operator.

Furthermore, we discussed involutions in EGG that are supposed to project an $N = 2$ background to an $N = 1$ one. Examples of these involutions are orbifoldings in M-theory or orientifoldings in type II. We found the explicit map between the original $SU(6)$ structure and its $SU(7)$ descendant. In particular, while L as well as $K_2 + iK_3$ are projected out, their tensor product produces ϕ , which defines the $SU(7)$ structure and survives the blow-up to a smooth geometry. The $N = 1$ Kähler potential and superpotential are then naturally determined by the $N = 2$ Kähler and hyper-Kähler potentials, and the prepotentials. We also determined the projection that creates negative tension objects with negative M5-brane charge in M-theory and observed that no $SU(7)$ structure can be defined in that case, i.e. one cannot describe the resolution of singularities from involutions other than orbifoldings in EGG. In particular, the orientifold singularities related to D6-branes in type IIA cannot be resolved, but the corresponding M-theory orbifold fixed points can. In other words, the pure existence of an extra coordinate enables to resolve the singularities of D6-branes and O6-planes. It seems in order to describe D-branes in

EGG one needs to introduce extra coordinates. For instance, while NS5-branes cannot be described in generalized geometry, they could in principle be described in doubled geometry. It would be interesting to understand the resulting doubled geometries in the presence of NS5-branes and their negative tension counterparts further. Even more challenging would be the realization of a 56-dimensional space that covariantizes $E_{7(7)}$ and could describe all branes in type II string theory or M-theory.

We pointed moreover out that there exists an intermediate generalized tangent bundle T_8 in M-theory that transforms under an $SL(8)$ subgroup of $E_{7(7)}$. From the type IIA point of view, this $SL(8)$ group contains the geometric transformations $SL(6)$ and the group $SL(2)$ transforming the four-dimensional axiodilaton $\tau = B_6 + i e^{-\phi}$. In this language, $N = 1$ backgrounds are described by a four-form on T_8 , $N = 2$ backgrounds by a real two-form and a complex four-form, i.e. they correspond to $Spin(7)$ and $SU(4)$ structures in eight dimensions. This suggests that there should exist a lift to an eight-dimensional space M_8 on which T_8 is the tangent bundle, similar to F-theory, whose volume is normalized everywhere. In the fashion described above, M_8 would not only geometrize D6-branes, but also some kind of exotic branes (as described in [13, 14]) that form a set of (p, q) -branes for the four-dimensional axiodilaton, similar to F-theory. It would be very interesting to understand such geometries further.

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Appendix

A $E_{7(7)}$ group theory

In the following we give relevant formulas for products of representations in the $SL(8)$ decomposition and their translation into the $SU(8)$ decomposition of spinors, following and extending [6].

A.1 $E_{7(7)}$ group theory in terms of $SL(8)$ representations

The $E_{7(7)}$ representations of interest are the fundamental **56**, the adjoint **133** and the **912**, whose decompositions under $SL(8)$ are given in (2.1), (2.2) and (2.3), respectively. In the following we denote objects in the fundamental representation by α , β , etc. and write them in terms of $SL(8)$ representations as

$$\alpha = (\alpha^{ab}, \alpha_{ab}) . \tag{A.1}$$

Similarly, the adjoint representation decomposes as

$$\mu = (\mu^a{}_b, \mu_{abcd}) . \quad (\text{A.2})$$

The **912** representation finally is given by

$$\phi = (\phi^{ab}, \phi^{abc}{}_d, \phi_{ab}, \phi_{abc}{}^d) . \quad (\text{A.3})$$

We will use the following notation for the product of representations:

$$\begin{aligned} (,) &: [\mathbf{rep} \otimes \mathbf{rep}]_1 , \\ \times &: [\mathbf{rep} \otimes \mathbf{rep}]_{133} , \\ \cdot &: [\mathbf{133} \otimes \mathbf{rep}]_{\mathbf{rep}} , \\ \otimes &: [\mathbf{56} \otimes \mathbf{133}]_{\mathbf{912}} , \\ \odot &: [\mathbf{912} \otimes \mathbf{133}]_{\mathbf{56}} , \\ \circ &: [\mathbf{912} \otimes \mathbf{56}]_{\mathbf{133}} , \end{aligned} \quad (\text{A.4})$$

where **rep** is any representation of $E_{7(7)}$.

The action of the adjoint on the fundamental representation, in other words the product $\mathbf{133} \times \mathbf{56} \rightarrow \mathbf{56}$, is given by

$$\begin{aligned} (\mu \cdot \alpha)^{ab} &= \mu^a{}_c \alpha^{cb} + \mu^b{}_c \alpha^{ac} + (\text{vol}_8^{-1} \lrcorner \mu)^{abcd} \alpha_{cd} , \\ (\mu \cdot \alpha)_{ab} &= -\mu^c{}_a \alpha_{cb} - \mu^c{}_b \alpha_{ac} - \mu_{abcd} \alpha^{cd} . \end{aligned} \quad (\text{A.5})$$

The symplectic invariant on the **56** reads

$$\langle \alpha, \beta \rangle = \alpha^{ab} \beta_{ab} - \alpha_{ab} \beta^{ab} . \quad (\text{A.6})$$

The trace in the adjoint is

$$(\mu, \nu) = \mu^a{}_b \nu^b{}_a - \frac{1}{6} (\text{vol}_8^{-1} \lrcorner \mu)^{abcd} \nu_{abcd} . \quad (\text{A.7})$$

The $\mathbf{56} \times \mathbf{56} \rightarrow \mathbf{133}$ reads

$$\begin{aligned} (\alpha \times \beta)^a{}_b &= \alpha^{ca} \beta_{cb} - \frac{1}{8} \delta_b^a \alpha^{cd} \beta_{cd} + \alpha_{cb} \beta^{ca} - \frac{1}{8} \delta_b^a \alpha_{cd} \beta^{cd} , \\ (\alpha \times \beta)_{abcd} &= -3(\alpha_{[ab} \beta_{cd]} + \frac{1}{4!} \epsilon_{abcdefgh} \alpha^{ef} \beta^{gh}) . \end{aligned} \quad (\text{A.8})$$

The action of the adjoint onto itself, i.e. the $\mathbf{133} \times \mathbf{133} \rightarrow \mathbf{133}$ is given by

$$\begin{aligned} (\mu \cdot \nu)^a{}_b &= (\mu^a{}_c \nu^c{}_b - \mu^c{}_b \nu^a{}_c) - \frac{1}{3} ((\text{vol}_8^{-1} \lrcorner \mu)^{acde} \nu_{bcde} - \mu_{bcde} (\text{vol}_8^{-1} \lrcorner \nu)^{acde}) , \\ (\mu \cdot \nu)_{abcd} &= 4(\mu^e{}_{[a} \nu_{bcd]e} - \nu^e{}_{[a} \mu_{bcd]e}) . \end{aligned} \quad (\text{A.9})$$

The product $\mathbf{56} \times \mathbf{133} \rightarrow \mathbf{912}$ is given by

$$\begin{aligned} (\alpha \otimes \mu)^{ab} &= \mu^a{}_c \alpha^{cb} + \mu^b{}_c \alpha^{ca} , \\ (\alpha \otimes \mu)^{abc}{}_d &= -3(\alpha^{[ab} \mu^{c]}{}_d - \frac{1}{3} \alpha^{e[a} \mu^b{}_e \delta^c]_d) + 2((\text{vol}_8^{-1} \lrcorner \mu)^{abce} \alpha_{ed} + \frac{1}{2} \alpha_{ef} (\text{vol}_8^{-1} \lrcorner \mu)^{ef[ab} \delta^c]_d) , \\ (\alpha \otimes \mu)_{ab} &= -\mu^c{}_a \alpha_{cb} - \mu^c{}_b \alpha_{ca} , \\ (\alpha \otimes \mu)_{abc}{}^d &= -3(\alpha_{[ab} \mu^c]{}^d - \frac{1}{3} \alpha_{e[a} \mu^e{}_b \delta^d]_c) + 2(\mu_{abce} \alpha^{ed} + \frac{1}{2} \alpha^{ef} \mu_{ef[ab} \delta^d]_c) . \end{aligned} \quad (\text{A.10})$$

The adjoint action $\mathbf{133} \times \mathbf{912} \rightarrow \mathbf{912}$ on the $\mathbf{912}$ is given by

$$\begin{aligned}
(\mu \cdot \phi)^{ab} &= \mu^a_c \phi^{cb} + \mu^b_c \phi^{ac} + \frac{2}{3}((\text{vol}_8^{-1} \lrcorner \mu)^{cde(a} \phi_{cde}^{b)}) , \\
(\mu \cdot \phi)^{abc}_d &= 3\mu^a_e \phi^{bc[e}_d - \mu^e_d \phi^{abc}_e + (\text{vol}_8^{-1} \lrcorner \mu)^{abce} \phi_{ed} + (\text{vol}_8^{-1} \lrcorner \mu)^{ef[ab} \phi_{efd}^{c]} \\
&\quad - (\text{vol}_8^{-1} \lrcorner \mu)^{efg[a} \phi_{efg}^b \delta_d^c] , \\
(\mu \cdot \phi)_{ab} &= -\mu^c_a \phi_{cb} - \mu^c_b \phi_{ac} + \frac{2}{3}(\mu_{cde(a} \phi_{b)}^{cde}) , \\
(\mu \cdot \phi)_{abc}^d &= -3\mu^e_{[a} \phi_{bc]e}^d + \mu^d_e \phi_{abc}^e + \mu_{abce} \phi^{ed} + \mu_{ef[ab} \phi_{c]}^{efd} - \mu_{efg[a} \phi_{b]}^{efg} \delta_c^d .
\end{aligned} \tag{A.11}$$

The product $\mathbf{912} \times \mathbf{133} \rightarrow \mathbf{56}$ reads

$$\begin{aligned}
(\phi \odot \mu)^{ab} &= -(\phi^{ac} \mu^b_c - \phi^{bc} \mu^a_c) - 2\phi_d^{abc} \mu^d_c \\
&\quad + \frac{2}{3}(\phi_{cde}^a (\text{vol}_8^{-1} \lrcorner \mu)^{cdeb} - \phi_{cde}^b (\text{vol}_8^{-1} \lrcorner \mu)^{cdea}) , \\
(\phi \odot \mu)_{ab} &= (\phi_{ac} \mu^c_b - \phi_{bc} \mu^c_a) - 2\phi_{abc}^d \mu^c_d \\
&\quad - \frac{2}{3}(\phi_{cde}^{cde} \mu_{cdeb} - \phi_{cde}^{cde} \mu_{cdea}) .
\end{aligned} \tag{A.12}$$

Similarly, the product $\mathbf{912} \otimes \mathbf{56} \rightarrow \mathbf{133}$ reads

$$\begin{aligned}
(\phi \circ \alpha)^a_b &= \alpha^{ca} \phi_{cb} + \alpha_{cb} \phi^{ca} + \alpha_{cd} \phi^{cda}_b - \alpha^{cd} \phi_{cdb}^a , \\
(\phi \circ \alpha)_{abcd} &= -4(\phi_{[abc}^e \alpha_{d]e} - \frac{1}{4!} \epsilon_{abcdefgh} \phi^{efg}_i \alpha^{hi}) .
\end{aligned} \tag{A.13}$$

The product $\mathbf{912} \otimes \mathbf{912} \rightarrow \mathbf{133}$ reads in the $SL(8)$ decomposition

$$\begin{aligned}
(\phi \times \psi)_b^a &= \phi^{ac} \psi_{cb} + \phi_{bc} \psi^{ca} + \frac{1}{3}(\phi_{cde}^a \psi^{cde}_b + \phi^{cde}_b \phi_{cde}^a) \\
&\quad - (\phi^{acd}_e \psi_{bcd}^e + \phi_{bcd}^e \psi^{acd}_e) \\
&\quad - \frac{1}{8} \delta_b^a (\phi^{cd} \psi_{cd} + \phi_{cd} \psi^{cd} - \frac{2}{3} \phi^{cde}_f \psi_{cde}^f - \frac{2}{3} \phi_{cde}^f \psi^{cde}_f) , \\
(\phi \times \psi)_{abcd} &= 4(\phi_{e[a} \psi_{bcd]}^e + \phi_{[bcd}^e \psi_{a]}^e + \frac{1}{4!} \epsilon_{abcdefgh} (\phi^{ei} \psi^{fgh}_i + \phi^{fgh}_i \psi^{ei})) \\
&\quad + 2(\phi_{f[ab}^e \psi_{cd]}^f + \frac{1}{4!} \epsilon_{abcdefgh} \phi^{efj}_i \psi^{ghi}_j) .
\end{aligned} \tag{A.14}$$

A.2 The relation to $SU(8)$ representations

The $SU(8)$ representation is spanned by anti-symmetric products γ_{ab} of the matrices γ_a that obey the Clifford algebra

$$\{\gamma_a, \gamma_b\}^\alpha_\beta = 2g_{ab} \delta^\alpha_\beta . \tag{A.15}$$

Furthermore, the gamma matrices γ_a fulfill

$$(\gamma^a)^\alpha_\beta (\gamma_a)^\gamma_\delta = \delta^\alpha_\delta \delta^\gamma_\beta . \tag{A.16}$$

Under $SU(8)$, the $\mathbf{56}$ decomposes according to

$$\begin{aligned}
\alpha &= (\alpha^{\alpha\beta}, \bar{\alpha}_{\alpha\beta}) , \\
\mathbf{56} &= \mathbf{28} \oplus \bar{\mathbf{28}} ,
\end{aligned} \tag{A.17}$$

while for the adjoint **133** we have

$$\begin{aligned}\mu &= (\mu^\alpha_\beta, \mu^{\alpha\beta\gamma\delta}, \bar{\mu}_{\alpha\beta\gamma\delta}) , \\ \mathbf{133} &= \mathbf{63} \oplus \mathbf{35} \oplus \bar{\mathbf{35}} .\end{aligned}\tag{A.18}$$

where $\mu^\alpha_\alpha = 0$ and $\bar{\mu}_{\alpha\beta\gamma\delta} = *_8\mu_{\alpha\beta\gamma\delta}$. Furthermore, we have for the **912** the $SU(8)$ decomposition

$$\begin{aligned}\phi &= (\phi^{\alpha\beta}, \phi^{\alpha\beta\gamma}_\delta, \bar{\alpha}_{\alpha\beta}, \bar{\phi}_{\alpha\beta\gamma}^\delta) , \\ \mathbf{912} &= \mathbf{36} \oplus \mathbf{420} \oplus \bar{\mathbf{36}} \oplus \bar{\mathbf{420}} ,\end{aligned}\tag{A.19}$$

Note that these are very similar to the $SL(8, \mathbb{R})$ decompositions (2.1), (2.2) and (2.3). To go from one to the other, we use for the **56** [3]

$$\begin{aligned}\alpha^{ab} &= (\alpha^{\alpha\beta} + \bar{\alpha}^{\alpha\beta})\gamma^{ab}_{\beta\alpha} , \\ \tilde{\alpha}_{ab} &= -i(\alpha^{\alpha\beta} - \bar{\alpha}^{\alpha\beta})\gamma^{ab}_{\beta\alpha} ,\end{aligned}\tag{A.20}$$

where we defined $\gamma^{ab}_{\beta\alpha} = C_{\beta\gamma}(\gamma^{ab})^\gamma_\alpha$ and $C_{\alpha\beta}$ is the matrix that induces transposition on spinors. In the **133**, if only the **63** adjoint representation of $SU(8)$ is nonzero, i.e. if $\mu_{\alpha\beta\gamma\delta} = 0$, one recovers the following $SL(8, \mathbb{R})$ components

$$\begin{aligned}\mu_{ab} &= \frac{i}{2}\mu^\alpha_\beta\gamma_{ab}^\beta{}_\alpha , \\ \mu_{abcd} &= \frac{1}{4}\mu^\alpha_\beta\gamma_{abcd}^\beta{}_\alpha ,\end{aligned}\tag{A.21}$$

where $\mu_{ba} = -\mu_{ab}$ and $*_8\mu_{abcd} = \mu_{abcd}$ (the symmetric and anti-self-dual pieces are obtained from the **70** representation $\mu^{\alpha\beta\gamma\delta}$) and $\mu_{ab} = g_{ac}\mu^c_b$. Similarly, if only the **36** and the **36** components are non-zero in the $SU(8)$ decomposition of the **912**, we get the $SL(8, \mathbb{R})$ components **36** and **420** in the following way

$$\begin{aligned}\phi^{ab} &= -\frac{1}{2}(\phi^{\alpha\beta} + \bar{\phi}^{\alpha\beta})C_{\alpha\beta}g^{ab} , \\ \phi^{abc}{}_d &= -\frac{3}{16}(\phi^{\alpha\beta} + \bar{\phi}^{\alpha\beta})(\gamma^{abc}{}_d)_{\alpha\beta} , \\ \phi_{ab} &= \frac{i}{2}(\phi^{\alpha\beta} - \bar{\phi}^{\alpha\beta})C_{\alpha\beta}g_{ab} , \\ \phi_{abc}{}^d &= \frac{3i}{16}(\phi^{\alpha\beta} - \bar{\phi}^{\alpha\beta})(\gamma_{abc}{}^d)_{\alpha\beta} .\end{aligned}\tag{A.22}$$

B Technical computations

B.1 The $N = 1$ superpotential

In this appendix we give the computation of the superpotential given in (3.55). We start from (3.54) where the differential operator is given by (3.38). The form of ϕ is given in (3.46 – 3.48). In order to compute (3.54), we consider first

$$\begin{aligned}D^C(A_{4B}^D\phi_{DC}^A + A_{4C}^D\phi_{BD}^A - A_{4D}^A\phi_{BC}^D) &= A_{4B}^D D^C\phi_{DC}^A - A_{4D}^A D^C\phi_{BC}^D \\ &\quad + (D^C A_{4B}^D)\phi_{DC}^A - (D^C A_{4D}^A)\phi_{BC}^D \\ &\quad + (D^C A_{4C}^D)\phi_{BD}^A + A_{4C}^D D^C\phi_{BD}^A ,\end{aligned}\tag{B.1}$$

where we used $Sp(56)$ indices.¹⁷ Now we can translate this back into $E_{7(7)}$ indices, rewriting the above equation as

$$D \circ (A_4 \cdot \phi) = A_4 \cdot (D \circ \phi) + (D \otimes A_4) \times \phi + (D \cdot A_4) \circ \phi + (A_4 \cdot D) \circ \phi , \quad (\text{B.2})$$

where we used the notation of Eq. (A.4) and in the last term the differential operator D acts on ϕ . If we use the form $A_4 = (0, \rho_8 \wedge A_3)$ and the form of the differential operator (3.38), we find that

$$D \cdot A_4 = 0 , \quad A_4 \cdot D = 0 . \quad (\text{B.3})$$

Now we can use a variant of the Hadamard formula to find

$$D\phi = e^{A_4} D(e^{-A_4} \phi) - e^{A_4} ([D \otimes A_4] \times (e^{-A_4} \phi)) + \frac{1}{2} e^{A_4} ((A_4 \cdot [D \otimes A_4]) \times (e^{-A_4} \phi)) + \dots , \quad (\text{B.4})$$

where we can compute the coefficients to be

$$\begin{aligned} [D \otimes A_4] &= (0, 2(\epsilon \cdot (\rho_8 \wedge dA_3)) \otimes (\rho_8), 0, 0) , \\ A_4 \cdot [D \otimes A_4] &= (0, 0, -2 *_8 (A_3 \wedge \rho_8 \wedge dA_3)(\rho_8) \otimes (\rho_8), 0) , \\ A_4 \cdot (A_4 \cdot [D \otimes A_4]) &= 0 . \end{aligned} \quad (\text{B.5})$$

The last equation actually puts all further terms in (B.4) to zero. From this together with (3.54), the superpotential can be computed to be

$$e^{K\phi/2} W = \frac{1}{2} \iota_{\rho_8} \phi_4 \wedge d\phi_4 + \frac{1}{2} \rho_8 \wedge \phi_4^c \wedge d^\dagger \phi_4 - 2i \phi_4 \wedge \iota_{\rho_8} dA_4 + (\iota_{\rho_8} A_4) \wedge dA_4 . \quad (\text{B.6})$$

In order to make the dependence on A_6 explicit, we use Formula (B.1) but now for $\hat{A} = (\rho_8 \otimes \hat{A}, 0)$ and note that $D^B \hat{A}_B = 0$ and $\hat{A}^D{}_C D^C = 0$. Therefore, we find

$$D \cdot (\hat{A} \cdot \phi) = \hat{A} \cdot (D \circ \phi) + [D \otimes \hat{A}] \times \phi . \quad (\text{B.7})$$

Furthermore, we compute

$$D \otimes \hat{A} = (0, 0, (\rho_8 \wedge dA_6) \rho_8 \otimes \rho_8, 0) , \quad (\text{B.8})$$

giving

$$\begin{aligned} e^{K\phi/2} W &= \frac{1}{2} \iota_{\rho_8} \phi_4^{(0)} \wedge d\phi_4^{(0)} + \frac{1}{2} \rho_8 \wedge \phi_4^{(0)} \wedge d^\dagger \phi_4^{(0)} + \rho_8 \wedge dA_6 \\ &\quad - 2i \phi_4^{(0)} \wedge \iota_{\rho_8} dA_4 + (\iota_{\rho_8} A_4) \wedge dA_4 . \end{aligned} \quad (\text{B.9})$$

From self-duality of $\phi_4^{(0)}$ we find that the first two terms actually agree. This means that we finally have

$$e^{K\phi/2} W = \iota_{\rho_8} \phi_4^{(0)} \wedge d\phi_4^{(0)} + \rho_8 \wedge dA_6 - 2i \phi_4^{(0)} \wedge \iota_{\rho_8} dA_4 + (\iota_{\rho_8} A_4) \wedge dA_4 . \quad (\text{B.10})$$

¹⁷Note that $E_{7(7)} \subset Sp(56)$.

B.2 The $N = 2$ prepotentials

In this appendix we compute the Killing prepotentials of the $N = 2$ theory given in (3.39). This computation is very similar to the one in Appendix B.1. We start with the second term in (3.13) where the differential operator is given by (3.38). The objects K_a and L defining the $SU(6)$ structure are given in (3.33) and (3.32), respectively. In order to compute (3.13), we consider first

$$D^B(A_4^A{}_D K^D{}_B - A_4^D{}_B K^A{}_D) = A_4^A{}_D D^B K^D{}_B + (D^B A_4^A{}_D) K^D{}_B - A_4^D{}_B D^B K^A{}_D - (D^B A_4^D{}_B) K^A{}_D, \quad (\text{B.11})$$

where we again used $Sp(56)$ indices. Translating this back into $E_{7(7)}$ indices, we find

$$D(A_4 \cdot K) = A_4 \cdot (DK) + [D \otimes A_4] \odot K + [D \cdot A_4] \cdot K + (A_4 \cdot D) \cdot K, \quad (\text{B.12})$$

where in the last term the differential operator D acts on K . The last two terms vanish due to $A_4 = (0, \rho_8 \wedge A_3)$, cf. (B.3). From the Hadamard formula we find

$$DK = e^{A_4} D(e^{-A_4} K) - e^{A_4} ([D \otimes A_4] \odot (e^{-A_4} K)) + \frac{1}{2} e^{A_4} ((A_4 \cdot [D \otimes A_4]) \cdot (e^{-A_4} K)), \quad (\text{B.13})$$

where the coefficients are given in (B.5). We can treat the transformations $\hat{A} = (\rho_8 \otimes \hat{A}, 0)$ using the same equations and (B.8), so that

$$DK = e^{A_{\text{shifts}}} D(e^{-A_{\text{shifts}}} K) - e^{A_{\text{shifts}}} ([D \otimes A_4] \odot (e^{-A_{\text{shifts}}} K)) + \frac{1}{2} e^{A_{\text{shifts}}} ((A_4 \cdot [D \otimes A_4]) \cdot (e^{-A_{\text{shifts}}} K)) - e^{A_{\text{shifts}}} ([D \otimes \hat{A}] \odot (e^{-A_{\text{shifts}}} K)). \quad (\text{B.14})$$

For the first term in (3.13) we have essentially to determine the scalar derivative (L, D) . From (3.32) and (3.38), we get

$$(L^{(0)}, D) = -e^{K_L} \text{vol}_8^{-1} \lrcorner (\frac{1}{3!} J^3 \wedge \rho_8 \wedge d) = e^{-K_L} \mathcal{L}_{\hat{v}^{(0)}}. \quad (\text{B.15})$$

From this together with (3.13), the Killing prepotentials can be computed to be

$$\begin{aligned} P^1 &= -4i\kappa J \wedge \rho_8 \wedge d \text{Im} \Omega_4^{(0)} - 4\kappa \iota_v (\text{Im} \Omega_4^{(0)}) \wedge \rho_8 \wedge dA_3, \\ P^2 &= e^{-K_L} ((\mathcal{L}_{\hat{v}^{(0)}} + \iota_{[\hat{v}^{(0)}, \hat{A}]} \text{Re} \Omega_4^{(0)}) \wedge \text{Im} \Omega_4^{(0)} - e^{-K_L} ((\mathcal{L}_{\hat{v}^{(0)}} + \iota_{[\hat{v}^{(0)}, \hat{A}]} \text{Im} \Omega_4^{(0)}) \wedge \text{Re} \Omega_4^{(0)} \\ &\quad + 4\kappa \rho_8 \wedge dA_6 - 2\kappa^2 e^{K_L} J \wedge J \wedge \rho_8 \wedge v^{(0)} \wedge dv^{(0)} \\ &\quad + 4\kappa (A_3 + i\kappa v^{(0)} \wedge J) \wedge \rho_8 \wedge dA_3, \\ P^3 &= -4i\kappa J \wedge \rho_8 \wedge d \text{Re} \Omega_4^{(0)} - 4\kappa \iota_v (\text{Re} \Omega_4^{(0)}) \wedge \rho_8 \wedge dA_3. \end{aligned} \quad (\text{B.16})$$

where we also used $[\mathcal{L}_{\hat{v}^{(0)}}, \iota_{\hat{A}}] = \iota_{[\hat{v}^{(0)}, \hat{A}]}$.

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